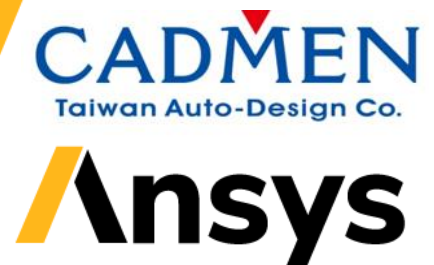


Using Ansys MAXWELL, Motion & Mechanical solve NVH Problems

虎門科技技術團隊

黃國豐

2022.04.08

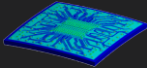




結構

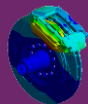
Mechanical Enterprise

耦和、聲場



Mechanical Premium

振動



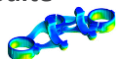
Mechanical Pro

靜態、熱傳



積層製造(2017併購3DSIM)

Additive Suite



Additive Print



材料資訊 (2019併購Granta Design)

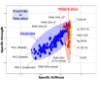
Granta Materials Data

模擬專用材料庫



CES Selector

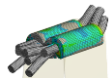
智慧選材工具



顯式求解器

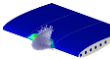
LS-DYNA (2019併購)

落下衝擊



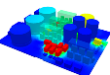
Autodyn (2005併購)

爆炸



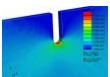
Sherlock (2019併購)

PCB可靠性



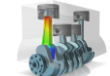
nCode DesignLife

高階疲勞



MBD for ANSYS

高階多體動力學

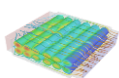


流體

計算流體力學

Fluent (2006併購)

泛用型計算流體分析



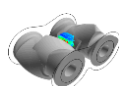
CFX (2003併購)

泛用型計算流體分析



Polyflow

高分子聚合物流體分析



FORTE

內燃機引擎燃燒分析



FENSAP-ICE(2015併購)

飛行器除冰分析



Chemkin (2014併購)

化學動力學模擬



旋轉機械應用

BladeModeler

互動式葉片設計



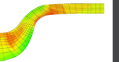
ICEPAK

電子產品散熱分析



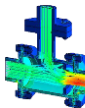
Vista TF

2D旋轉機械分析



CFD Post

CFD專用後處理



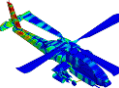
電磁場

(2008併購Ansoft)

電磁場分析

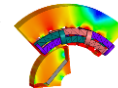
HFSS

高頻電磁場



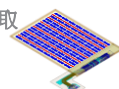
Maxwell 3D

低頻電磁場



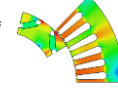
Q3D Extractor

寄生參數萃取



Maxwell 2D

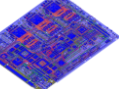
低頻電磁場



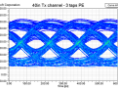
PCB電路板電磁場

Siwave

電路板設計

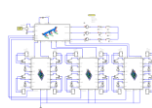


Designer



系統控制分析

Twin Builder



機電參數設計

RMxpert

馬達設計

PExprt

變壓器設計

Optimetrics

參數分析



光學

(2018併購OPTIS)

SPEOS Enterprise

可視化



SPEOS Premium

光譜分析、

逆追跡



SPEOS Pro

亮度、光源



SPEOS for NX

SPEOS for Creo Parametric

VRXPERIENCE

Driving Simulator



Headlamp



HMI



Sensor

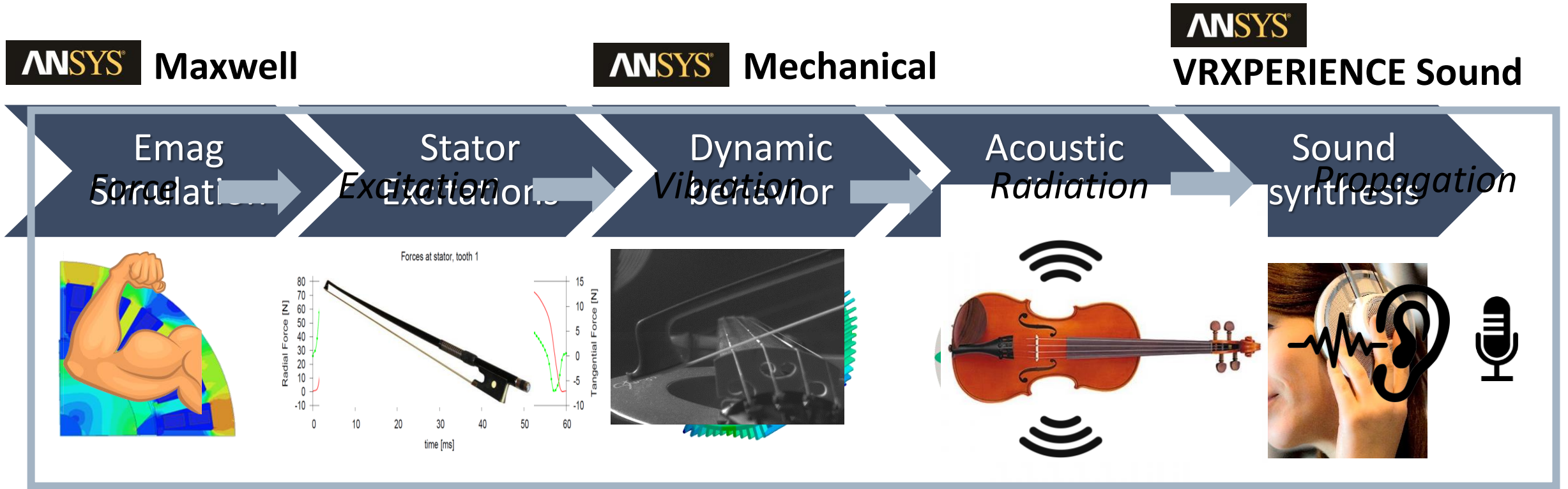


Perceived Quality



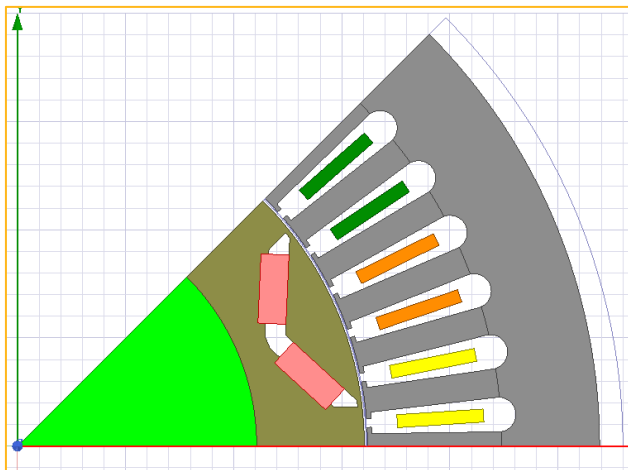
ANSYS Workbench

/ Listen to CAE

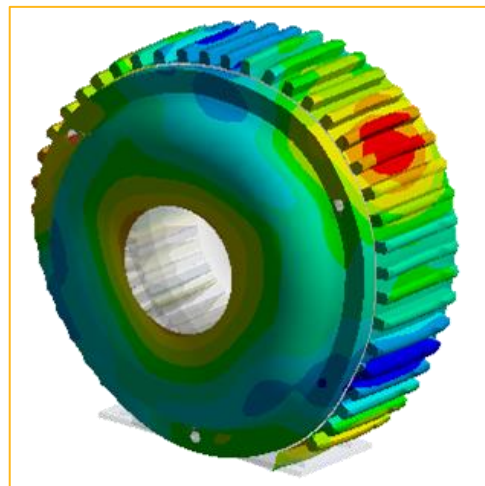


流程

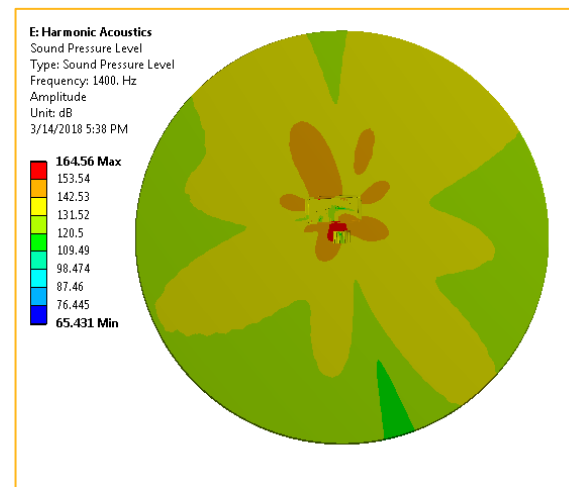
1. Magnetic Field Solution



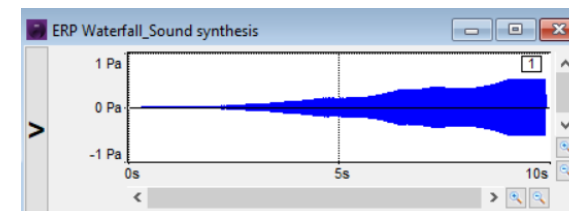
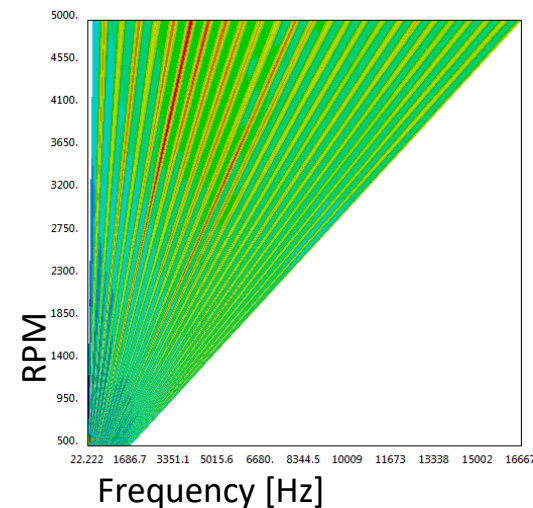
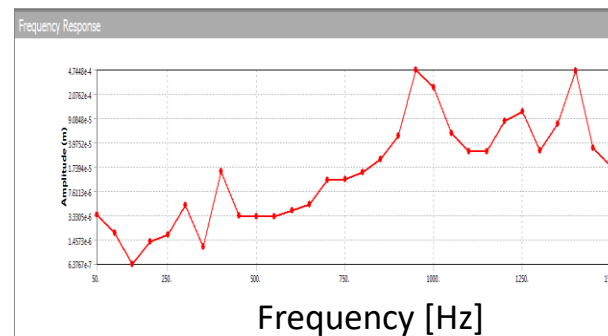
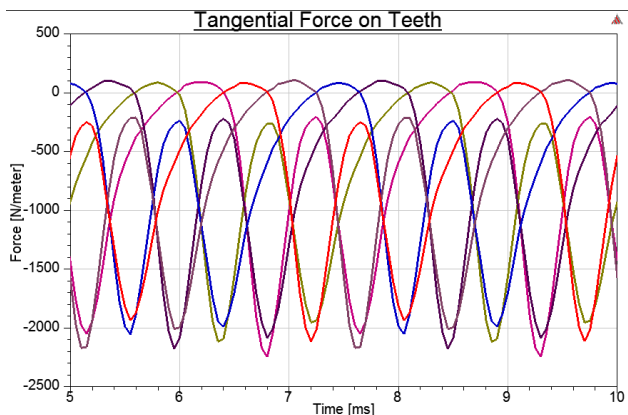
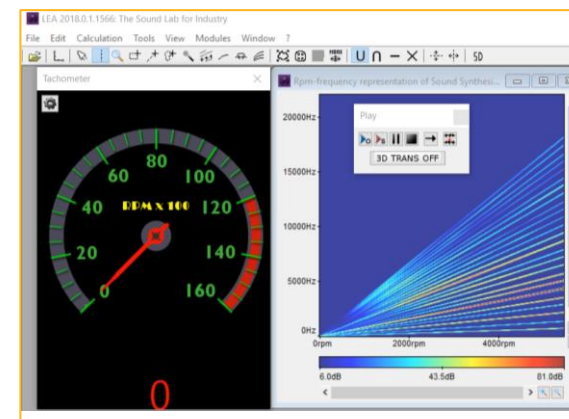
2. Modal and Vibration



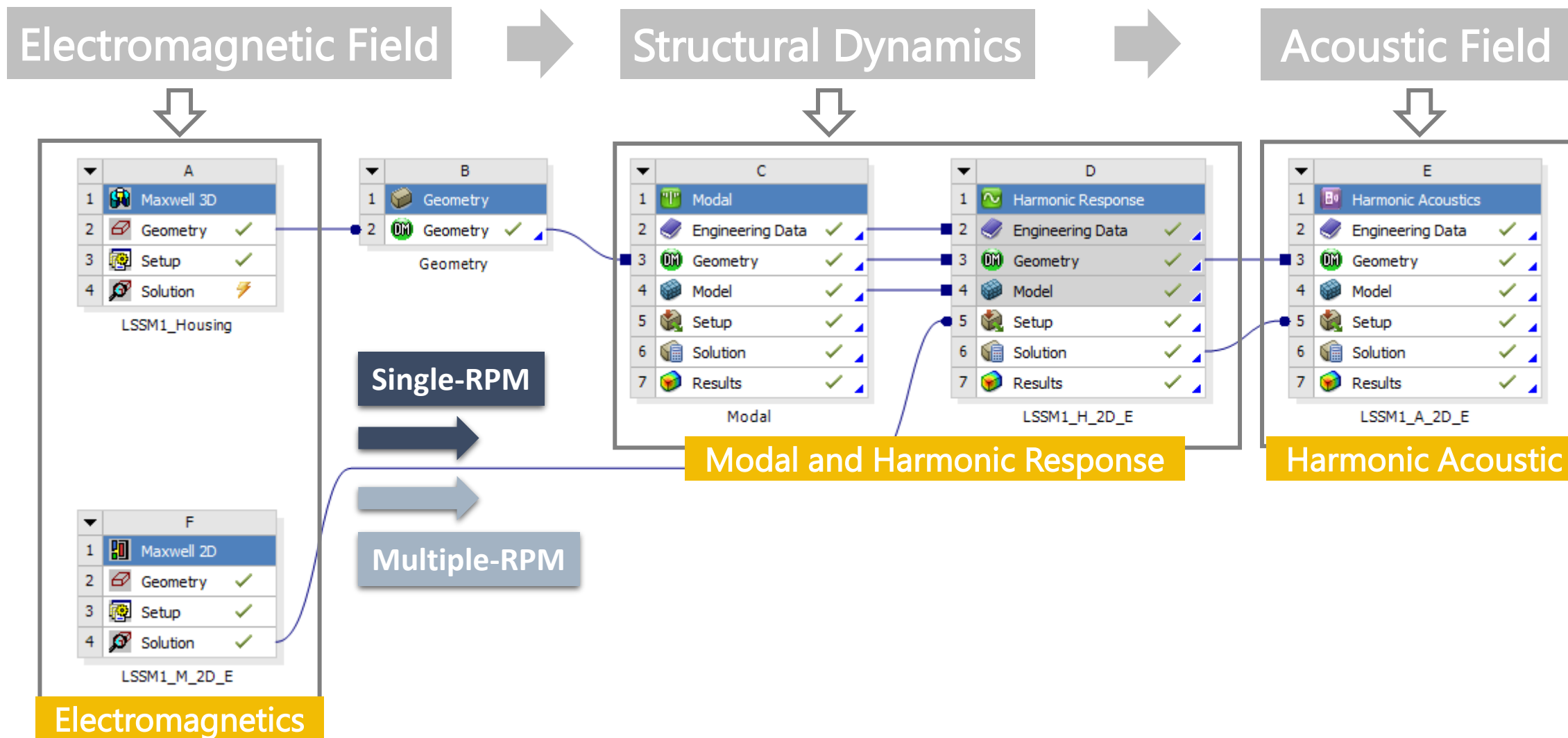
3. Acoustic



4. VRxperience



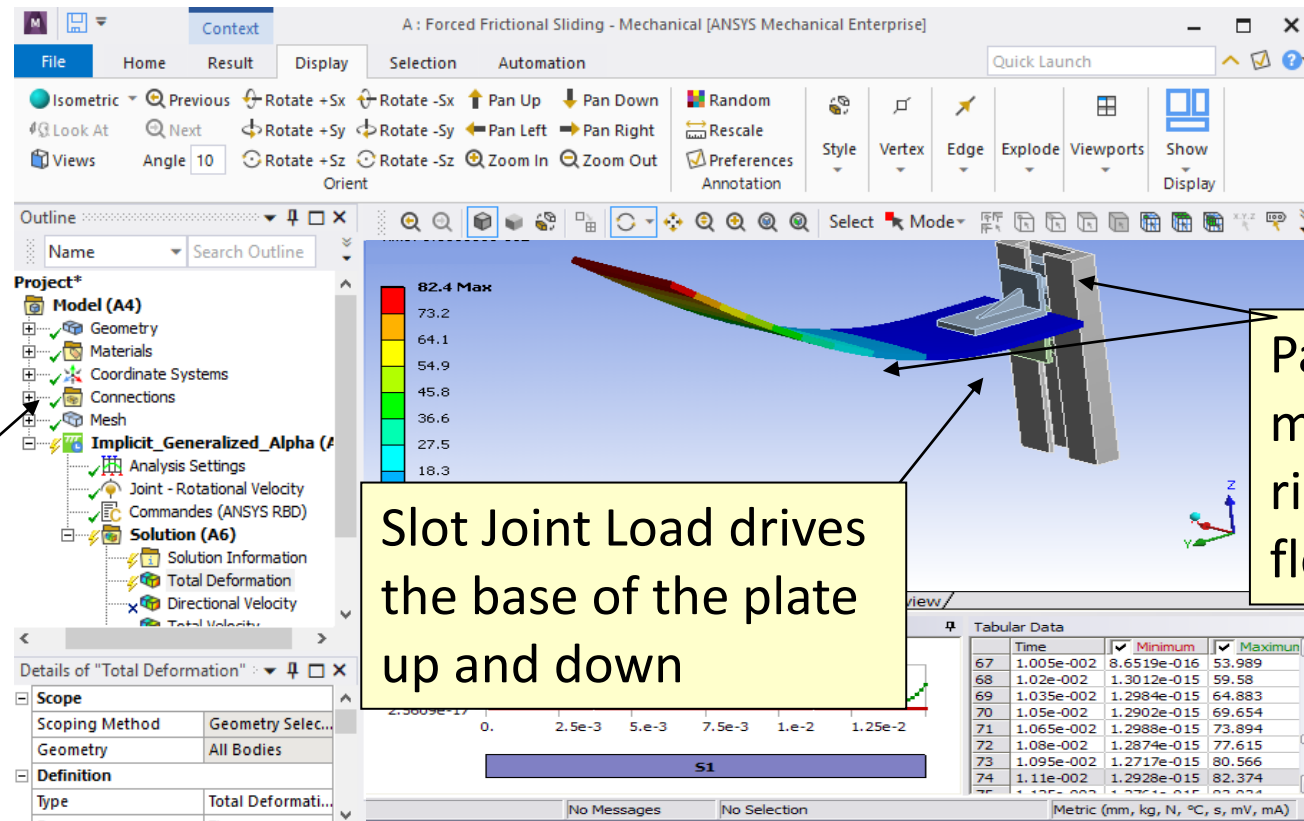
Project schematic



ANSYS Motion

What is Multibody Dynamic (MBD) Analysis?

- It is a means of analyzing the dynamic behavior of a system of interconnected bodies consisting of rigid and/or flexible components.

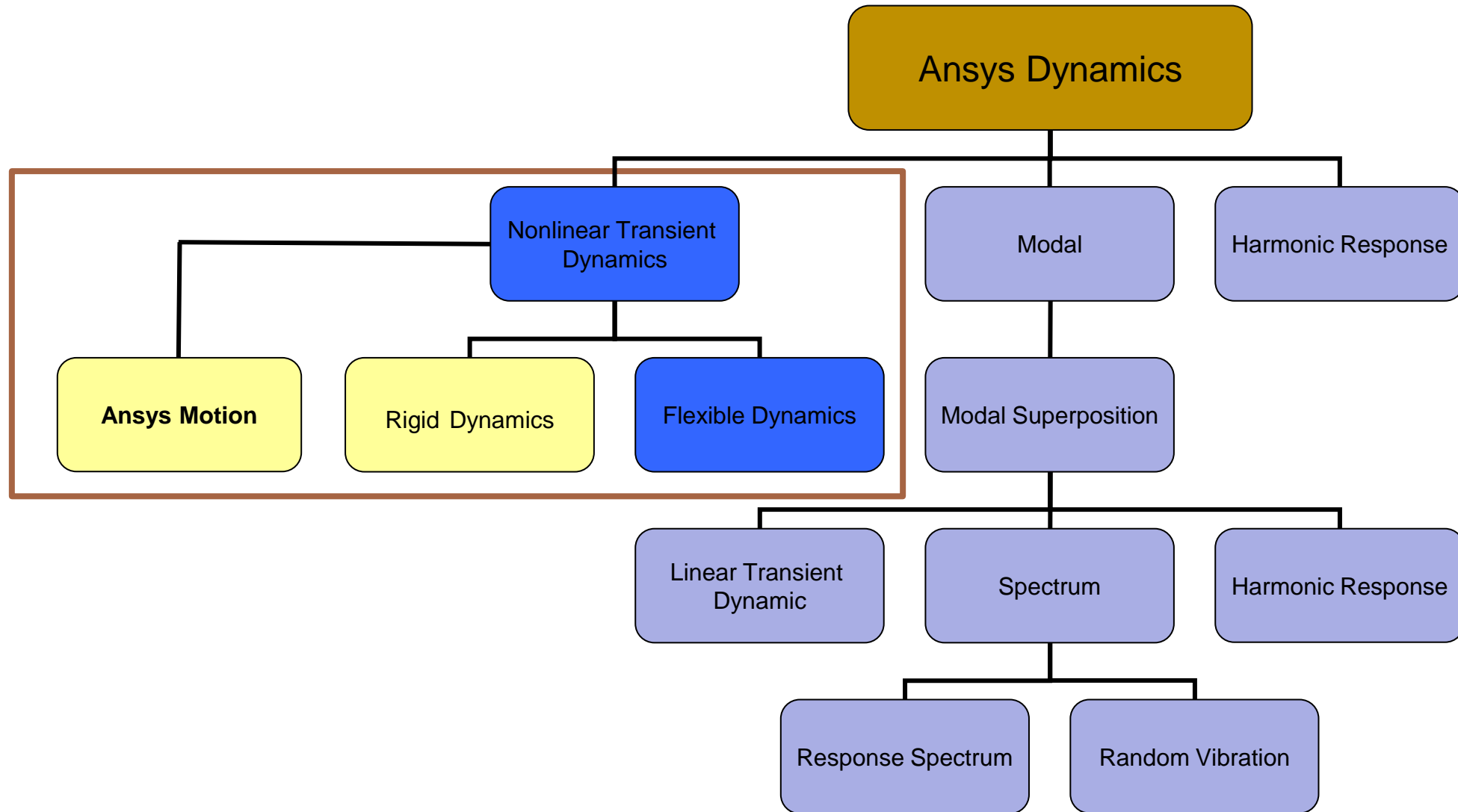


Parts are connected at Joints which allow some relative motion

Slot Joint Load drives the base of the plate up and down

Parts are modeled as rigid and/or flexible

/ Introduction

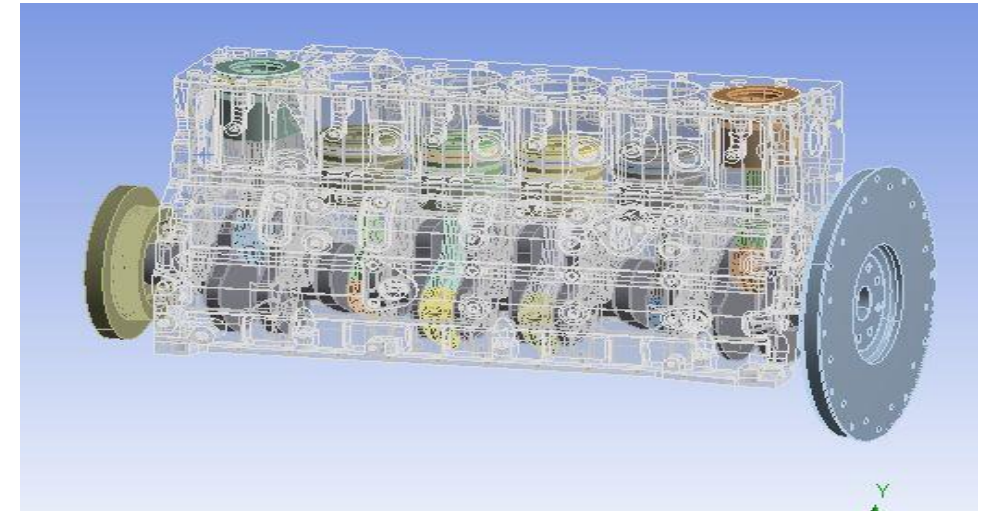
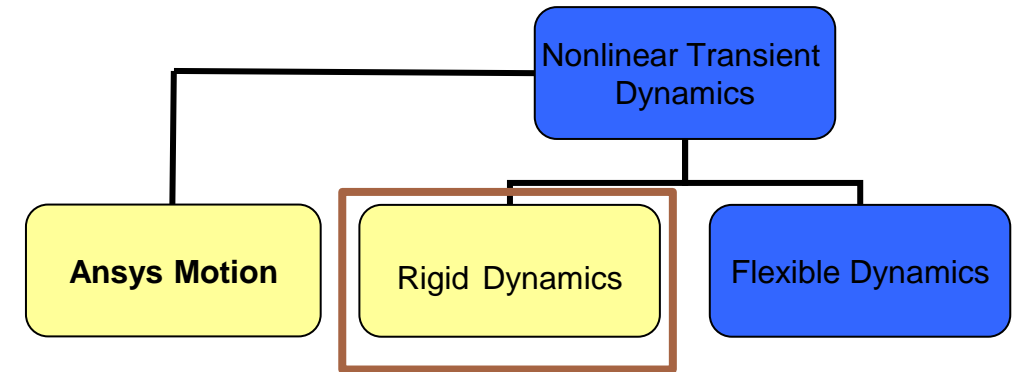


/ Introduction

Three Multibody Dynamic Analysis types are available:

Rigid Multibody Dynamics

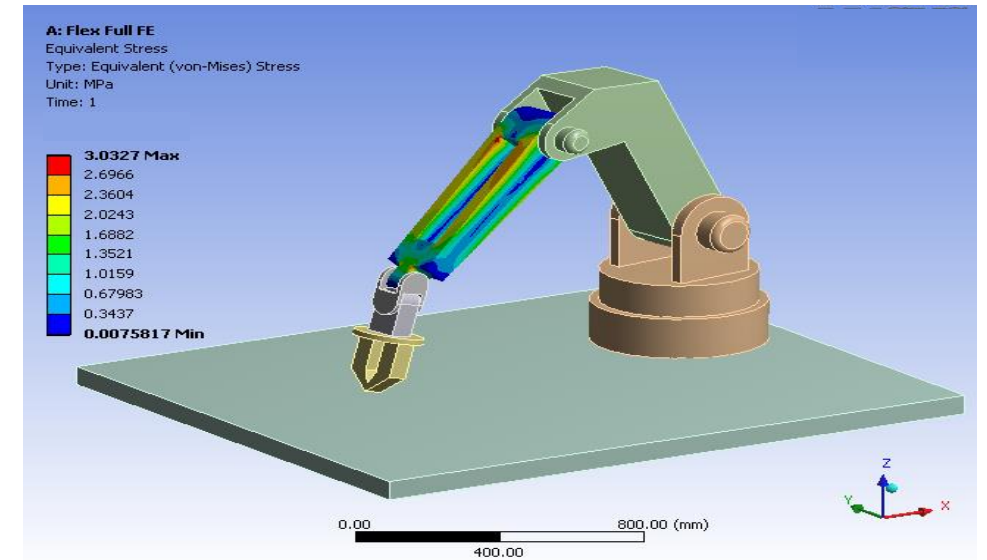
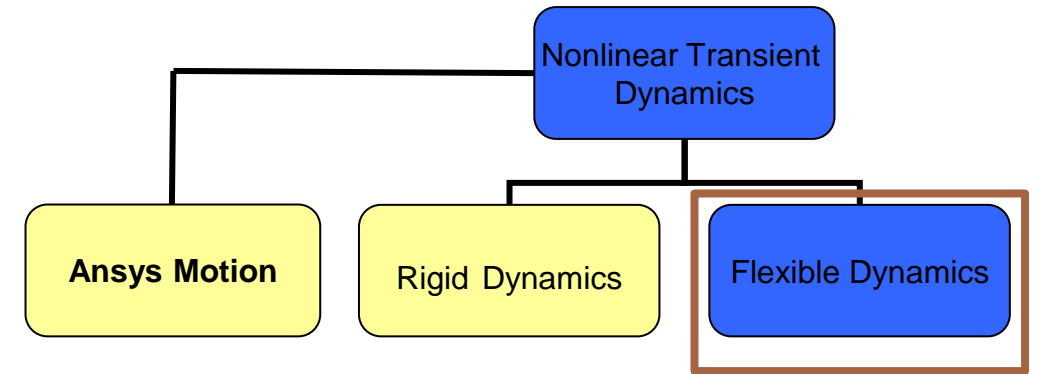
- Consists mainly of rigid bodies
- May include condensed parts (CMS super elements)
- Motion due only to joints/contacts
- Goal is determination of Motion and Forces
- Few degrees of freedom, fast solves
- Best suited for short duration large deformation analysis
- Large deformation and large rotations capabilities
- Based on energy conservation



/ Introduction

Flexible Multibody Dynamics

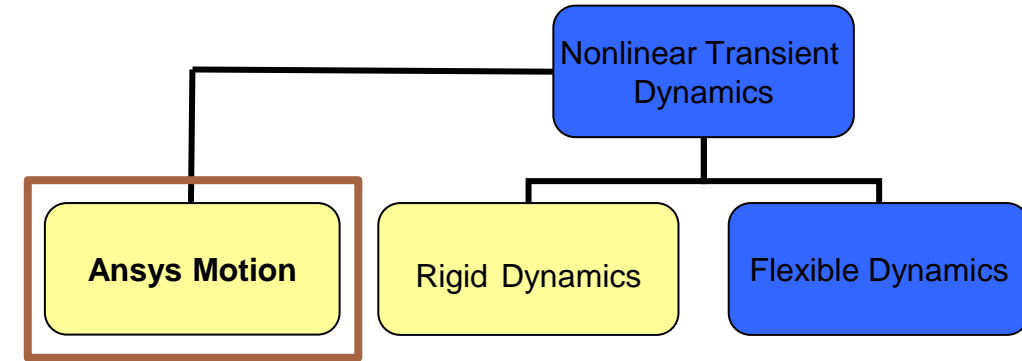
- Consists of rigid and/or flexible bodies
- All types of nonlinearities are allowed
- Motion due to joints/contacts and flexible part deformation
- Goal is determination of Motion, Forces, Deformations, and Stresses
- Longer solves, but more results data
- CMS available to speed-up solves



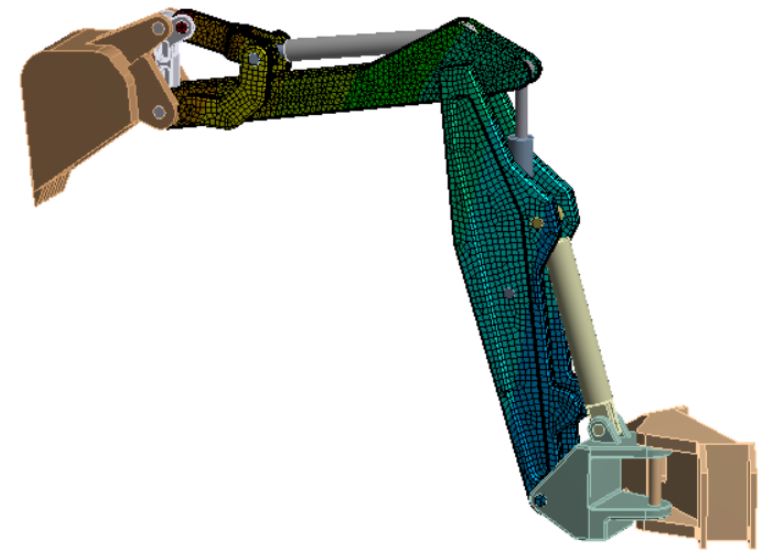
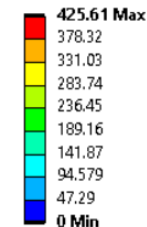
/ Introduction

Ansys Motion

- Consists of rigid bodies, modal bodies and/or nodal bodies
- All types of nonlinearities are allowed
- Motion due to joints/contacts and flexible part deformation
- Goal is determination of Motion, Forces, Deformations, and Stresses
- Recommended for high-speed large rotation systems
- Robust for 3D contacts systems
- Can be performed by “Motion” analysis system
- Specific toolkits available



A: ANSYS Motion
Total Deformation 6
Type: Total Deformation
Unit: mm
Time: 10.



/ Ansys Motion

Main Package Capabilities

- Multibody Dynamics
- Strength/Fatigue
- NVH (Linear & Transient)
- Heat Transfer
- FMI/FMU

Advanced toolkits

LINKS



Tracks, Chains And Belts

DRIVETRAIN



Gears, Bearings, Shafts

CAR



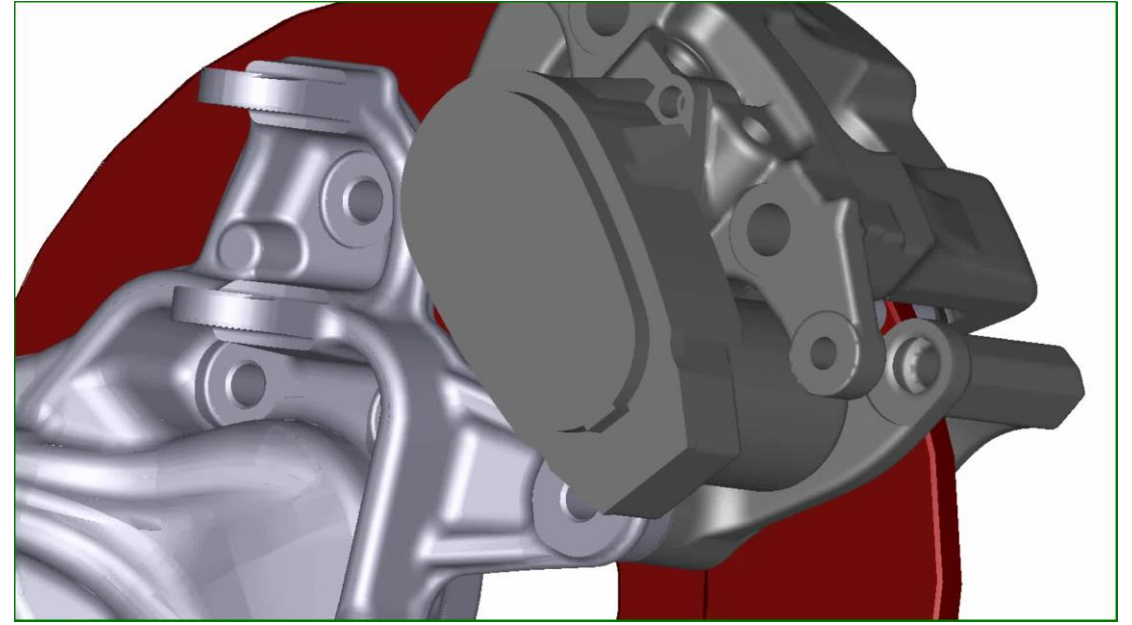
Auto Ride & Handling

EASYFLEX



Meshfree Flexible Solver

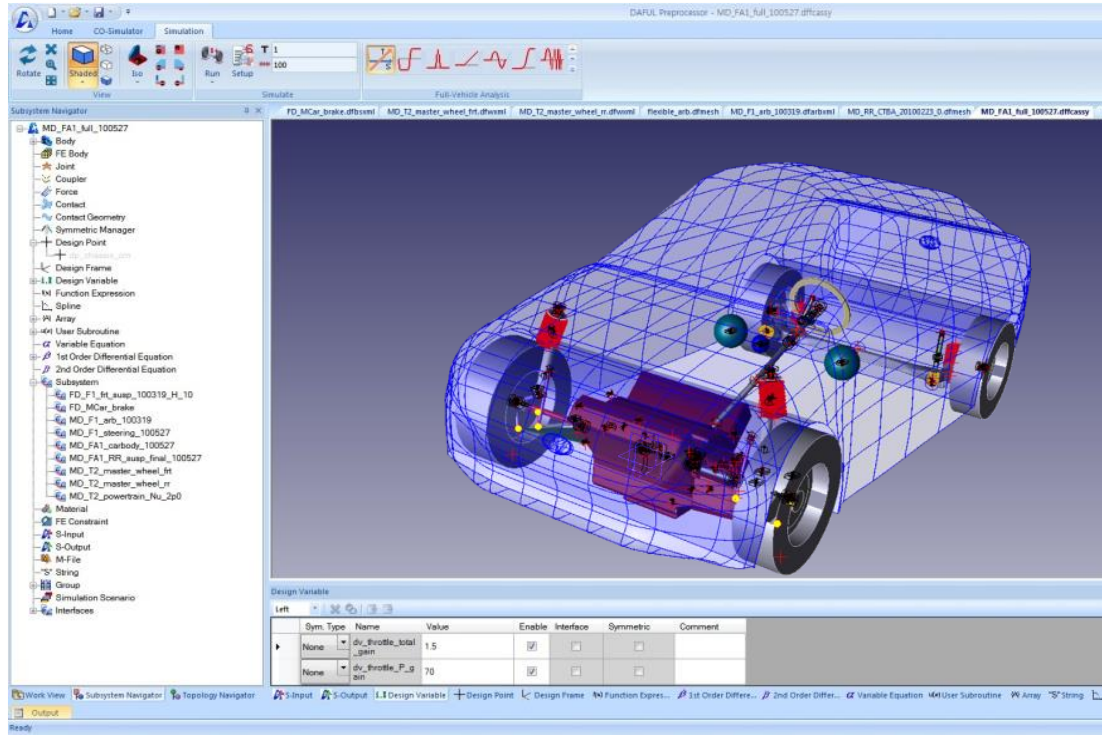
Transient Stress Analysis of Brake Assembly



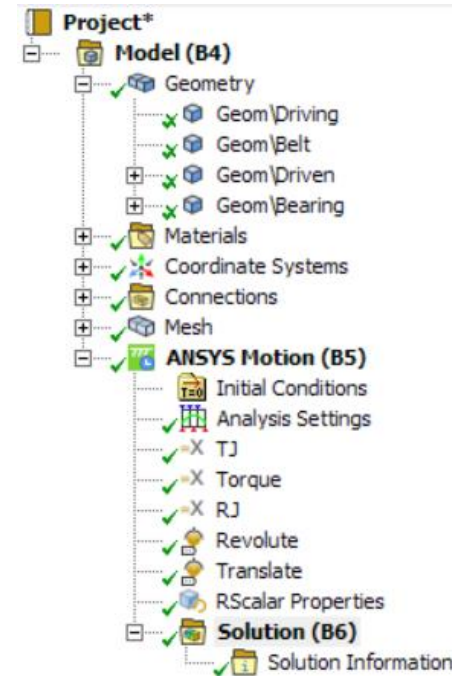
Ansys Motion ACT Application

Preprocessor

Ansys Motion Standalone



Ansys Motion in Workbench



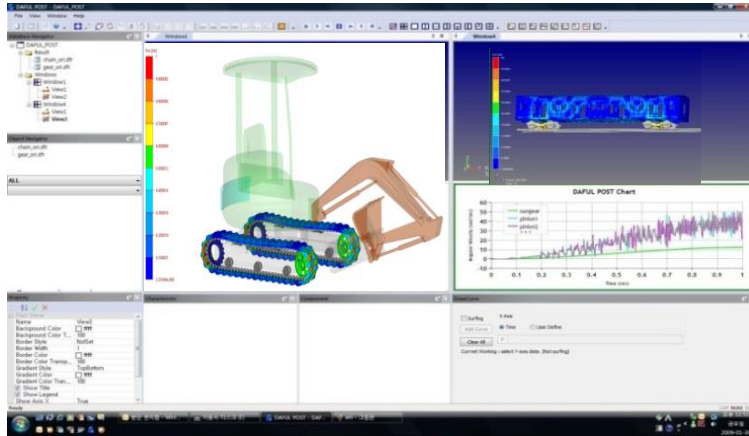
Provides the power of the Ansys Workbench and Mechanical Environments to facilitate the preprocessing of Ansys Motion models.

Ansys Motion ACT Application

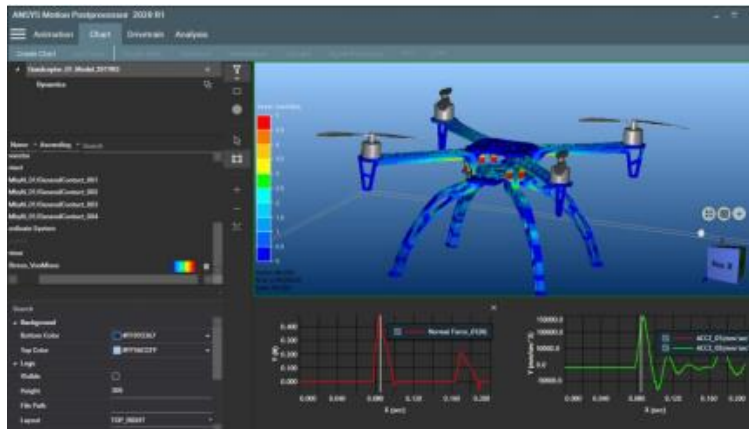
Postprocessor

Ansys Motion Standalone

Classic postprocessor



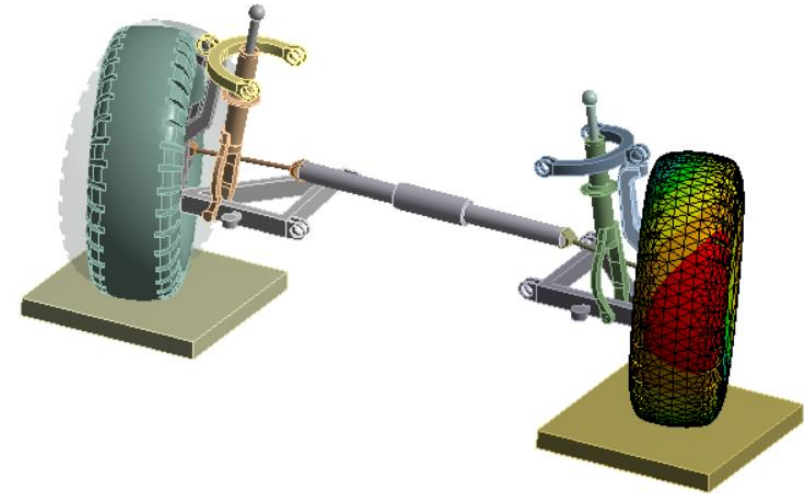
New postprocessor



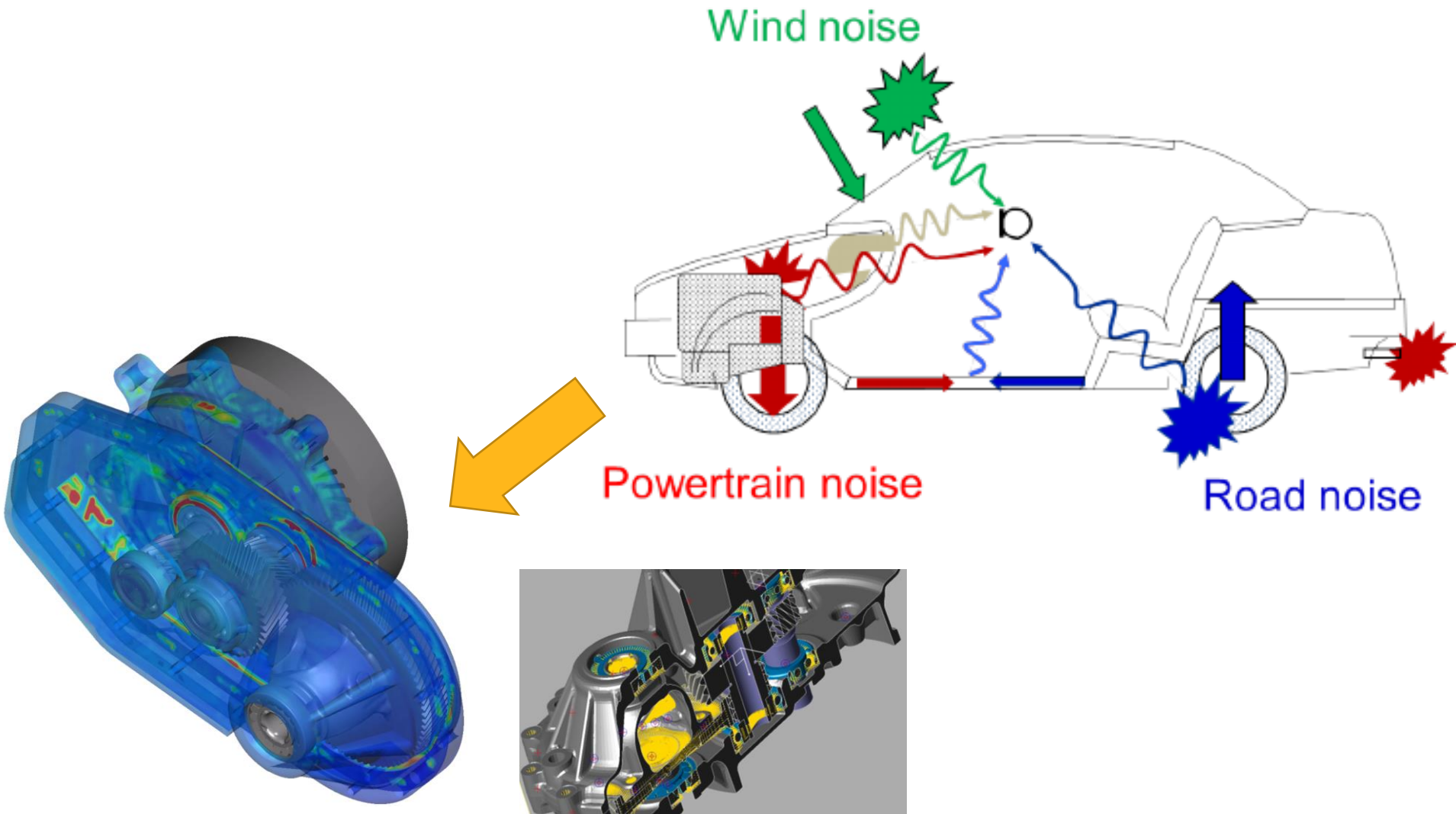
Ansys Motion in Workbench

A: ANSYS Motion
Total Deformation
Type: Total Deformation
Unit: mm
Time: 1.

165.17 Max
146.81
128.46
110.11
91.759
73.407
55.055
36.704
18.352
6.2835e-10 Min



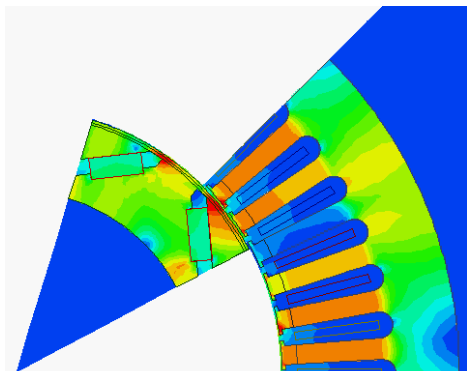
- Only deformation, velocity and acceleration are available in Mechanical
- Ansys Motion postprocessor can be opened directly from Mechanical for others results





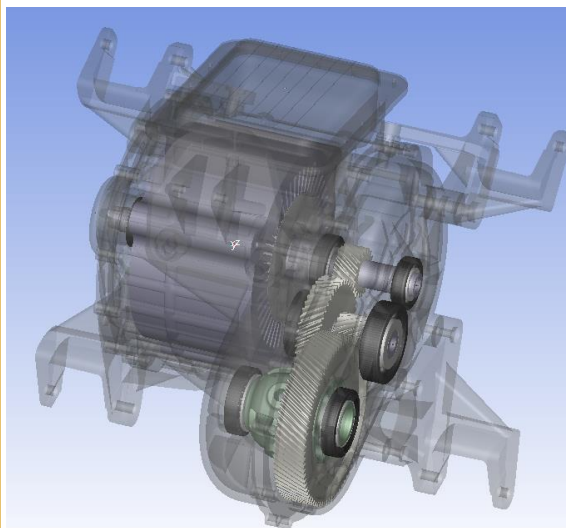
Ansys Maxwell

- Compute electromagnetic force of a rotor and stator



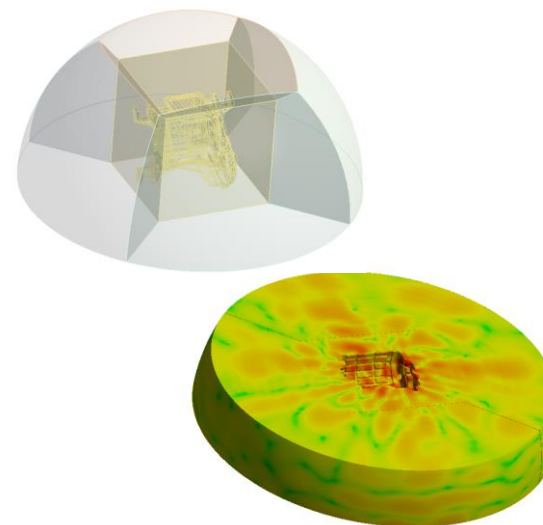
Ansys Motion

- MBD simulation of a complete assembly of E-powertrain system
- Whole system driven by EM force
- Surface velocity calculated and exported



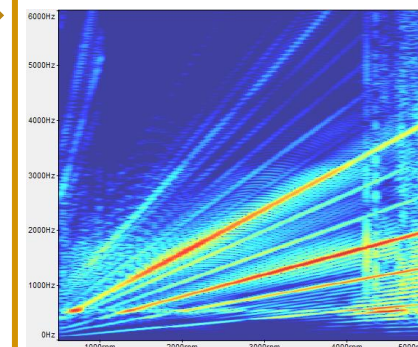
Ansys Mechanical

- High-fidelity acoustic simulation based on surface velocity calculated by Motion
- Calculate propagated sound pressure in near and far field



Ansys VRX Sound

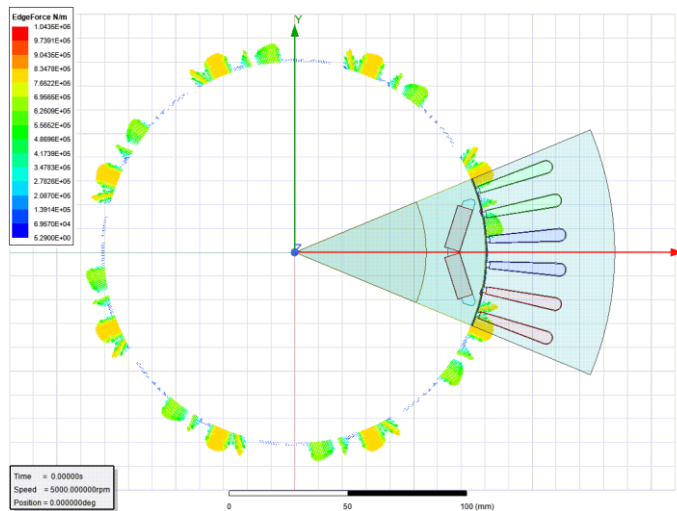
- Order analysis
- Psychoacoustics analysis
- Mix and comparison with measurements



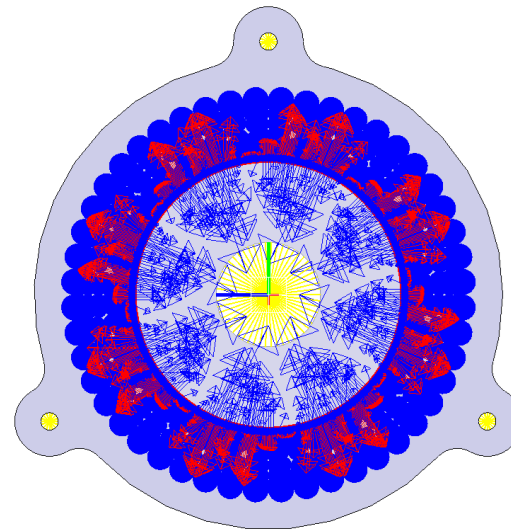
Noise Sources of E-Drivetrain

- Electromagnetic (EM) Force of a E-Motor
 - EM force on a rotor and stator excites a structure
 - The vibration of the rotor and stator transmitted to a housing which generates noise
 - Generally induces high-frequency vibration and noise

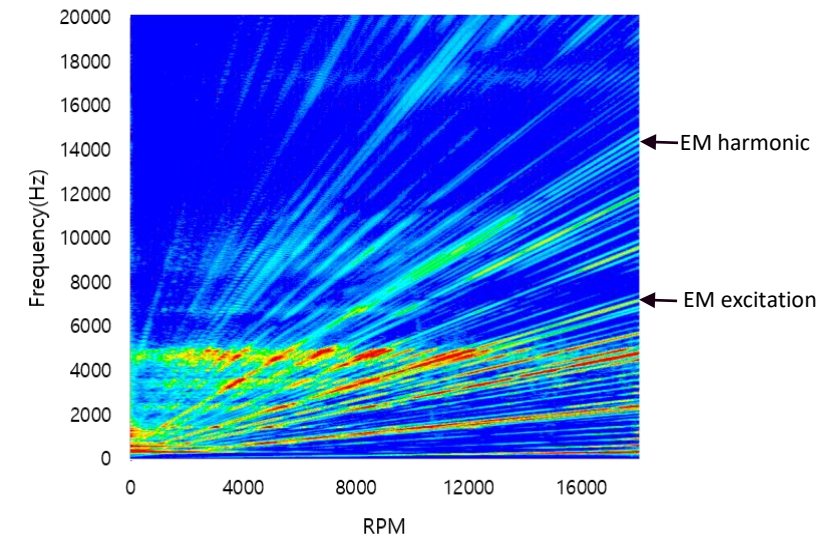
EM Forces



EM Forces mapped to the structure



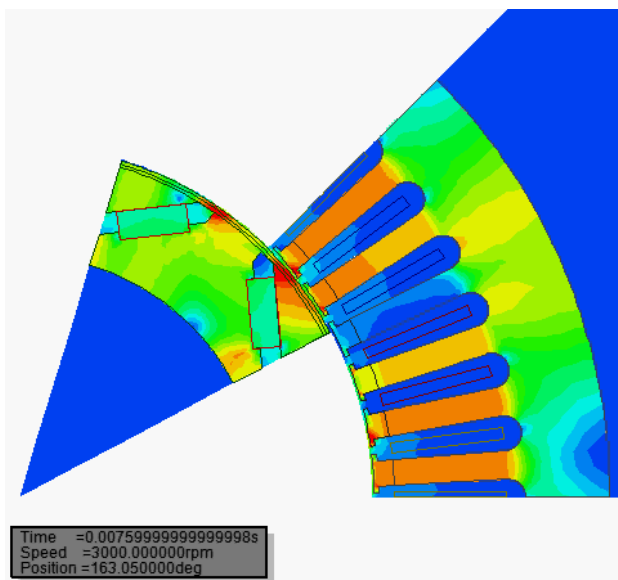
Acceleration Waterfall



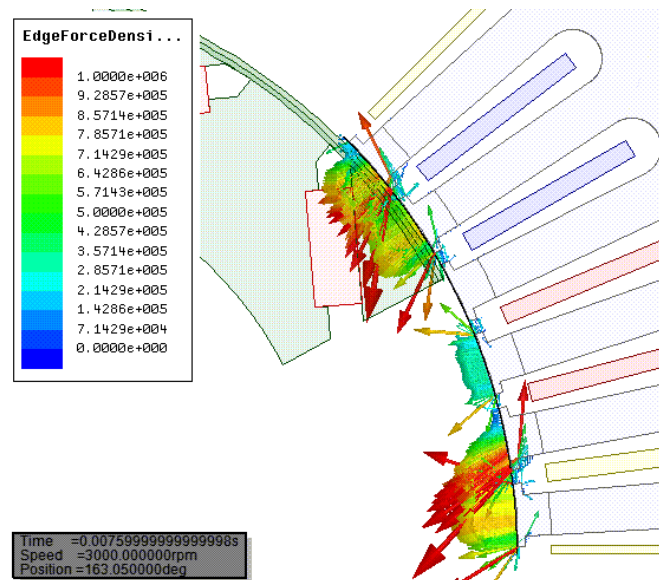
E-Drivetrain NVH Workflow: Electromagnetics

- Ansys Maxwell: Flagship Low-Frequency Electromagnetic Solver
 - Calculation of electromagnetic (EM) forces on both a rotor and stator in time domain
 - 2D/3D and Periodic/Full model of a motor can be simulated.
 - The effect of skew, eccentricity, switching frequency can be considered.

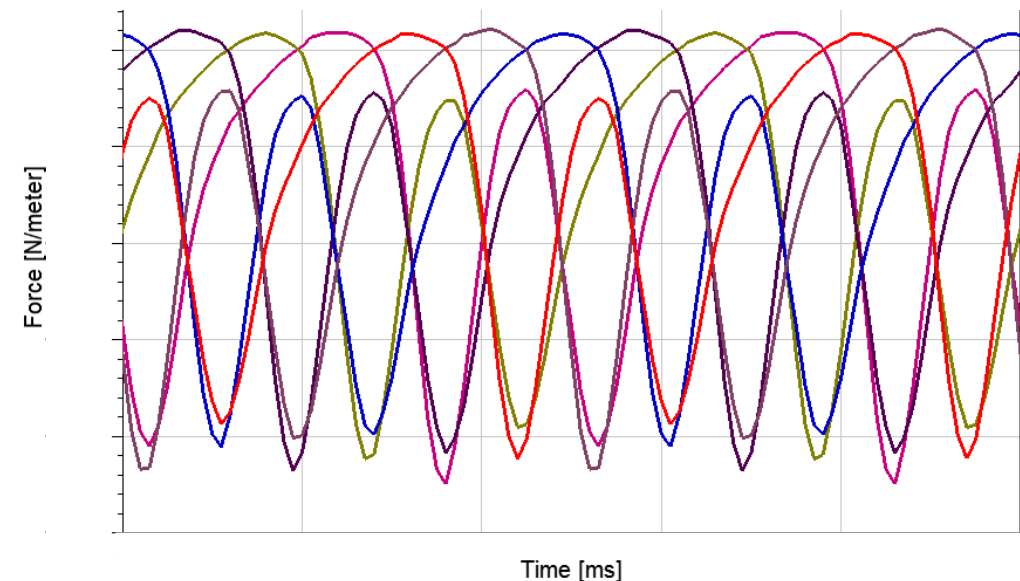
Magnetic Field



Magnetic Forces



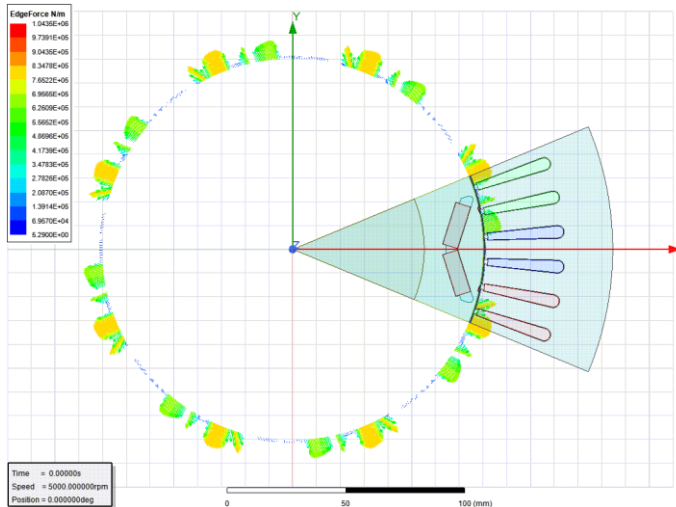
Force on Stator Teeth



E-Drivetrain NVH Workflow: EM Force Mapping

- EM force mapped from an electromagnetics model to a FE structural model
- The entire E-drivetrain system driven and excited by the mapped EM forces
- Object-based (lumped force) and mesh-based (distributed force) mapping available

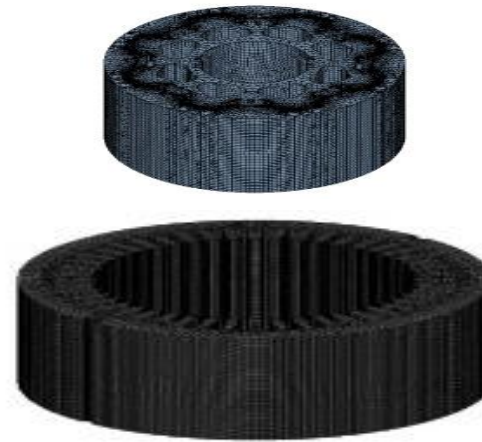
Ansys Maxwell



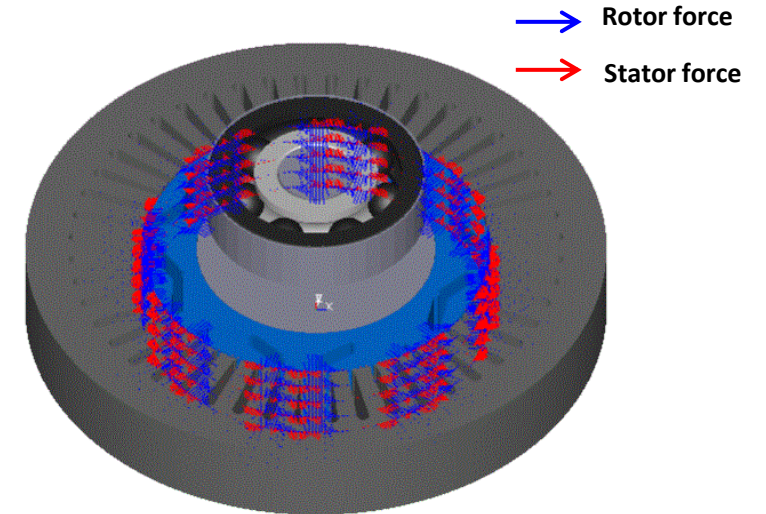
EM force calculation

Transfer
EM Forces

Ansys Motion



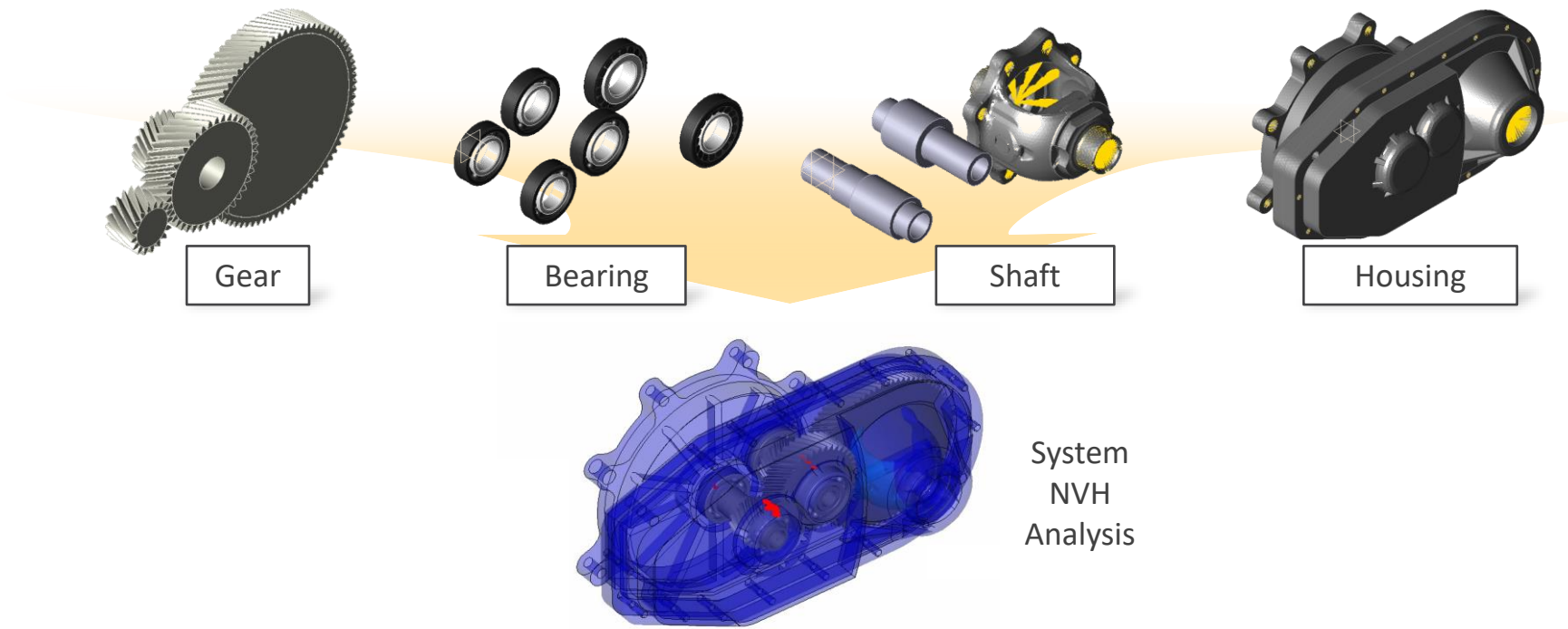
FE bodies of a rotor and stator



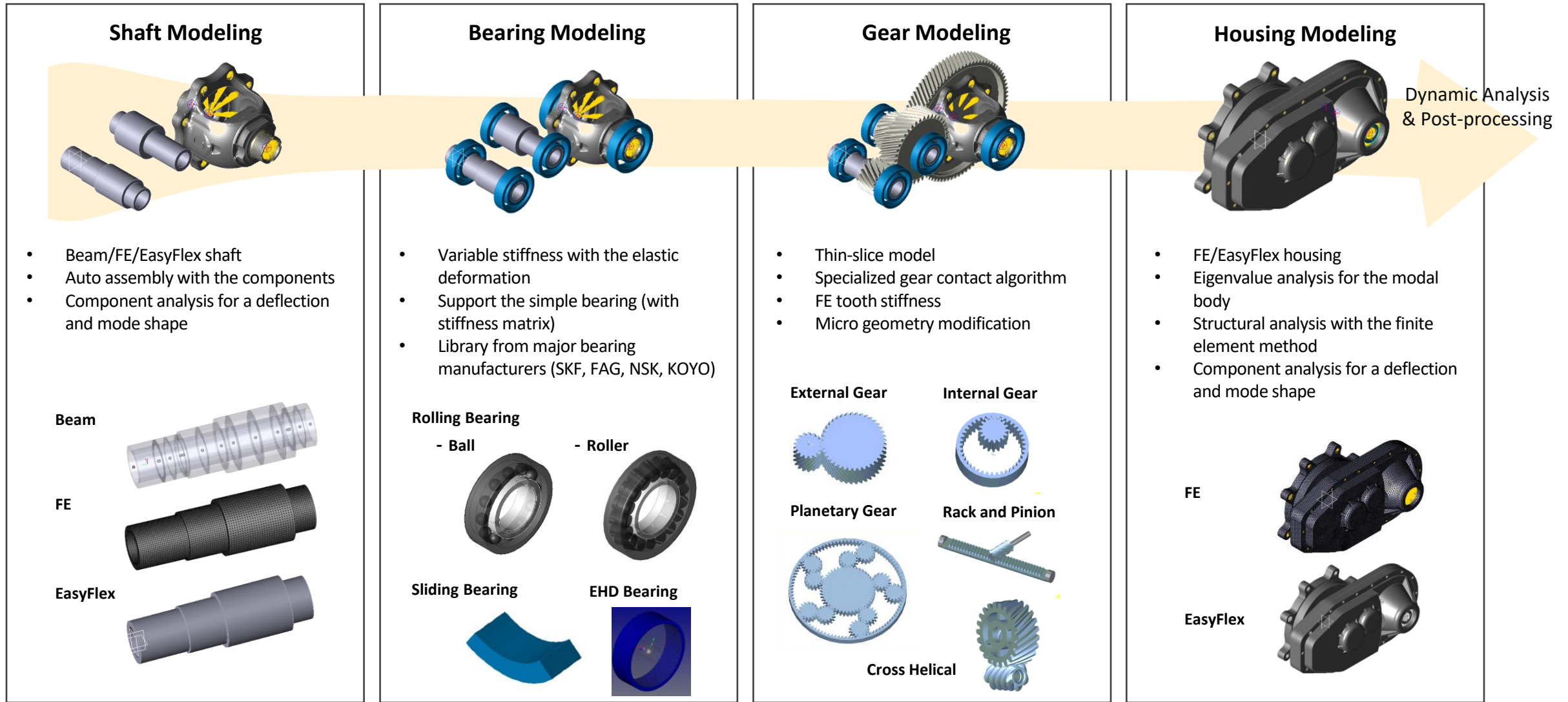
Mapped EM forces

E-Drivetrain NVH Workflow: Multi-Body Dynamics

- Ansys Motion: The 3rd Generation Multi-Body Dynamics (MBD) Solver
 - General-purpose MBD solver
 - Provides the advanced toolkits: Links, *Drivetrain*, Car and EasyFlex



E-Drivetrain NVH Workflow: Multi-Body Dynamics



Dynamic Analysis & Post-processing

Setting gearset

Gear Set

Creation method
☒ New ☐ KISSsoft ☐ Copy

Gear Type: Helical
Hand of Helix: ☒ Right ☐ Left
Number of Gear: 2 Set

Specification

Gear Name	Gear1	Gear2
Module(m)	2.402	
Pressure Angle(α)	16.5	
Helix Angle(β)	34	
Number of Teeth(z1, z2)	19	43
Profile Shift Coefficient(x1, x2)	0.23	-0.1949
Face Width(w1, w2)	30	28
Center Distance	90	

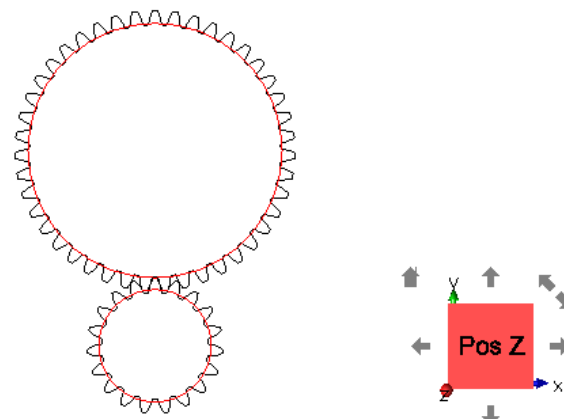
Color:

Name: GearSet_01

☒ Show Designer

✓ Apply 🔄 Apply & Restart ✗ Cancel

Reducer.dfdtn GearSet_01.dfhgs



General Gears Gear Pairs

Name of Gear Set: GearSet_01
Number of Gear: 2

	1st	2nd
Gear name	Gear1	Gear2

Number of Gear Pair: 1

	GearPair1
Driving	Gear1
Driven	Gear2

Color: ...

Show advanced option

General Gears Gear Pairs Advanced Option

Basic Involute Tool Tolerance Modification Material Run Out/Pitch Error Web Tooth Stiffness Summary

	Gear1	Gear2
<input type="radio"/> Addendum Coefficient	1	1
<input checked="" type="radio"/> Actual Tip Diameter	62.6	129.2
<input type="radio"/> Dedendum Coefficient	1.25	1.25
<input checked="" type="radio"/> Actual Whole Depth	6.6	6.6
<input checked="" type="radio"/> Profile Shift Coefficient	0.23	-0.1949
<input type="radio"/> Back Lash	0	
Tool Tip Radius	0.2	0.2

✓ Apply

Setting rolling

Bearing

Data type: User Input

Bearing Type

Inner Color:

Outer Color:

Name: Rolling_Input_01

☒ Show Designer

Apply Apply & Restart Cancel

General Dimensions Internal Component Analysis

Bore (d)	35	Ball pitch diameter (d_{in})	48.5
Outer diameter (D)	62	Number of ball (N_b)	10
Width (B)	14.5	Ball diameter (D_w)	10
		Inner raceway shoulder diameter (d_1)	41
		Outer raceway shoulder bore (D_1)	56
		Rounding radius (r_1)	0.5

Apply

General Dimensions Internal Component Analysis

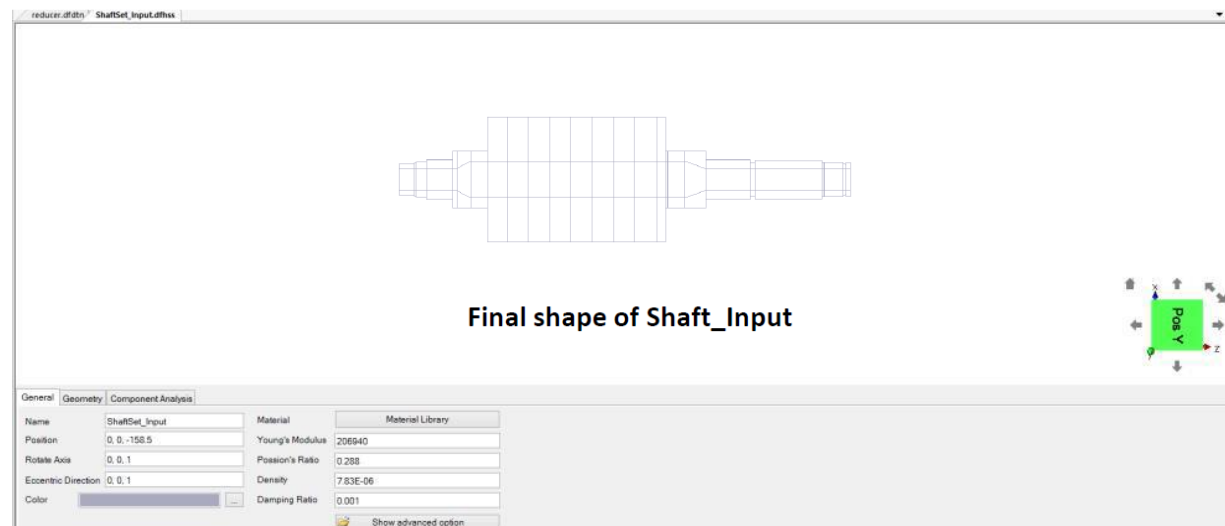
Outer raceway groove radius (r_o) 5.2


Inner raceway groove radius (r_i) 5.1


Radial internal clearance (p_d) User input 0 um


Apply

Setting shaft

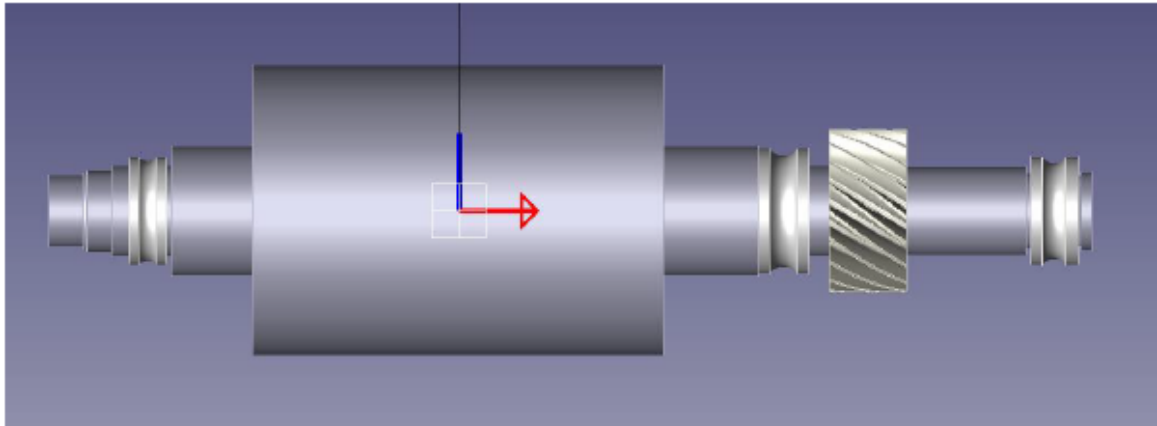


	Section_01	Section_02	Section_03	Section_04
Name	Section_01			
Length	13.5			
Eccentricity	0			
Cross Section	HOLLOW CIRCULAR ▼			
Outer Diameter	27.5			
Inner Diameter	20			
 Apply				

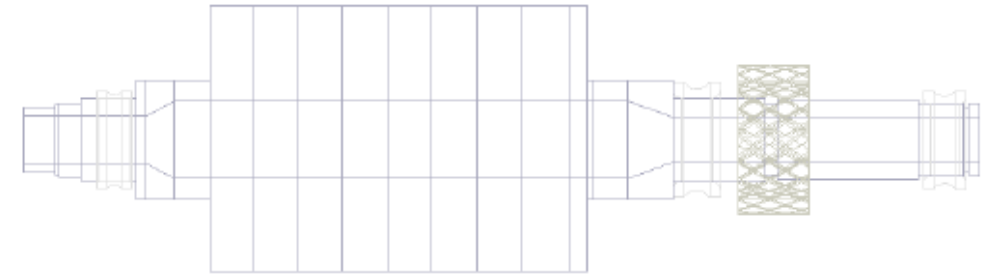
	Section_01	Section_02	Section_03	Section_04
Name	Section_02			
Length	1.5			
Eccentricity	0			
Cross Section	HOLLOW TAPERED ▼			
Outer Start Diameter	29.26794			
Outer End Diameter	31			
Inner Start Diameter	20			
Inner End Diameter	20			
 Apply				

	Section_01	Section_02	Section_03	Section_04
Name	Section_03			
Length	9.4			
Eccentricity	0			
Cross Section	HOLLOW CIRCULAR ▼			
Outer Diameter	31			
Inner Diameter	20			
 Apply				

Assemble



Shape in Designer



Shape in Subsystem

Ansys / MOTION



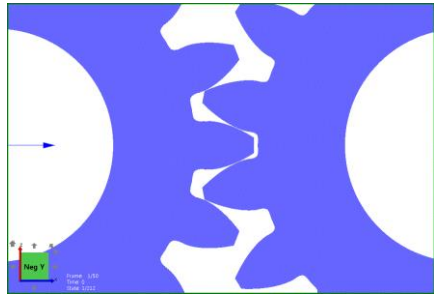
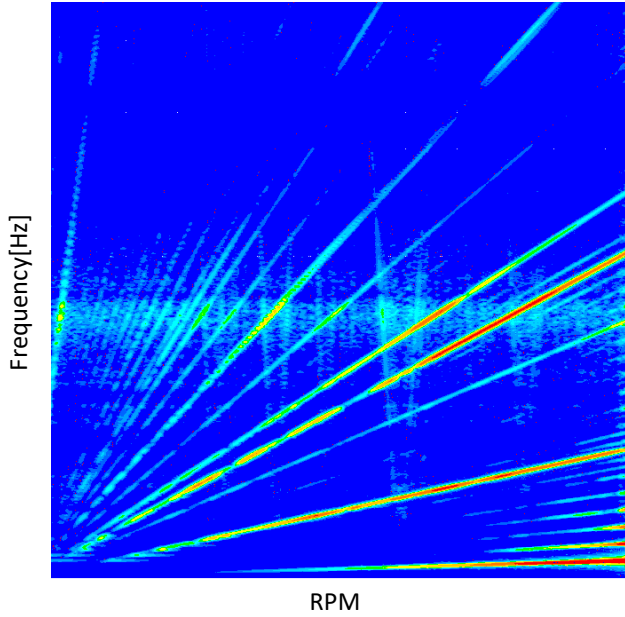
Motor Speed (RPM)



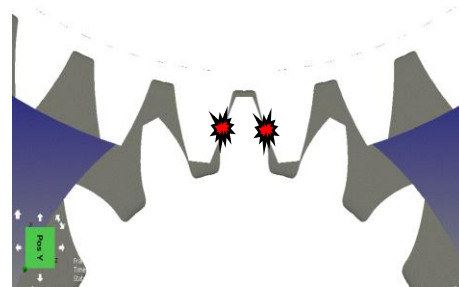
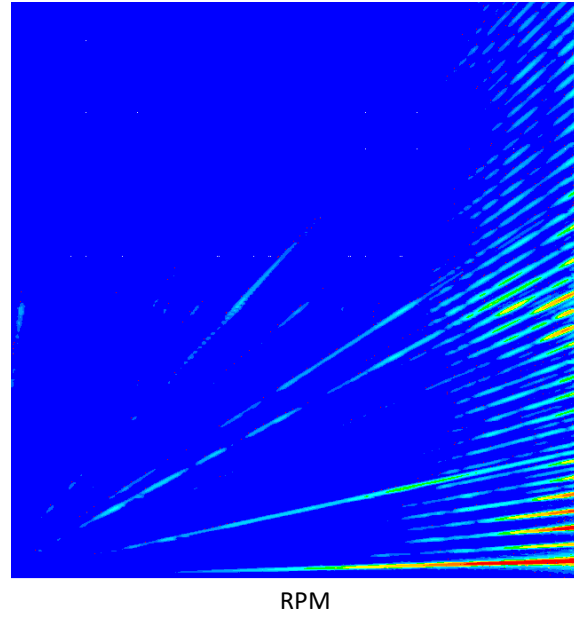
Noise Sources of E-Drivetrain

- Gear Train

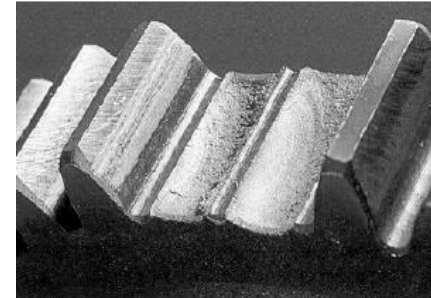
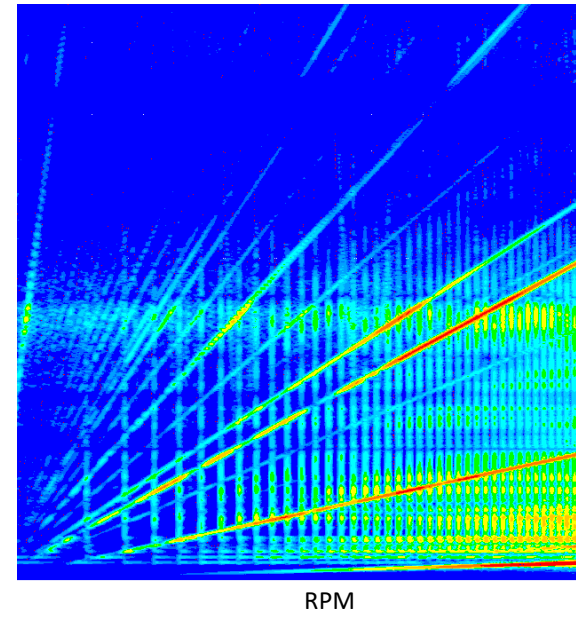
Gear whine



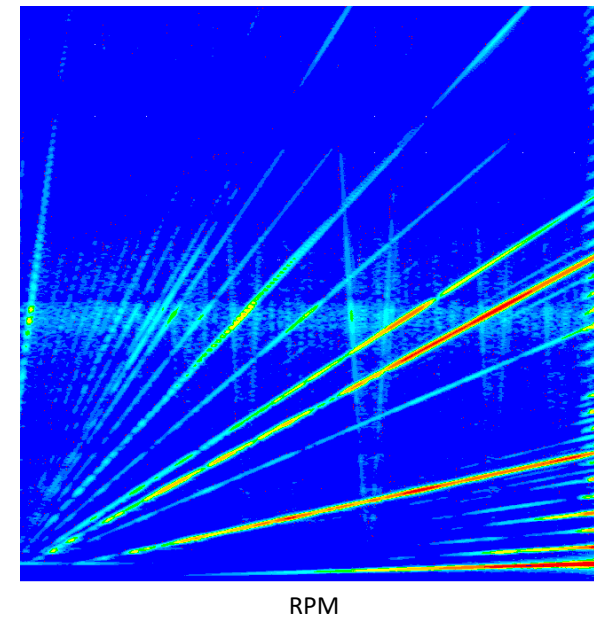
Gear rattle



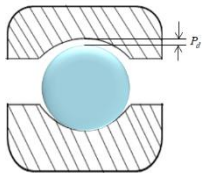
Gear fault




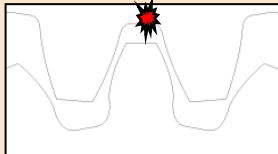

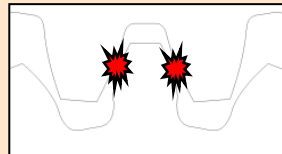
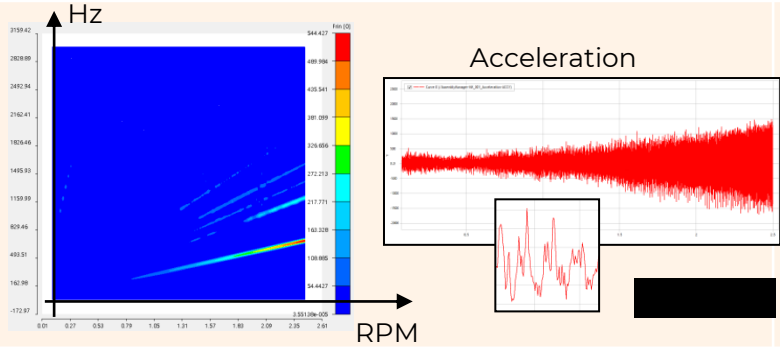
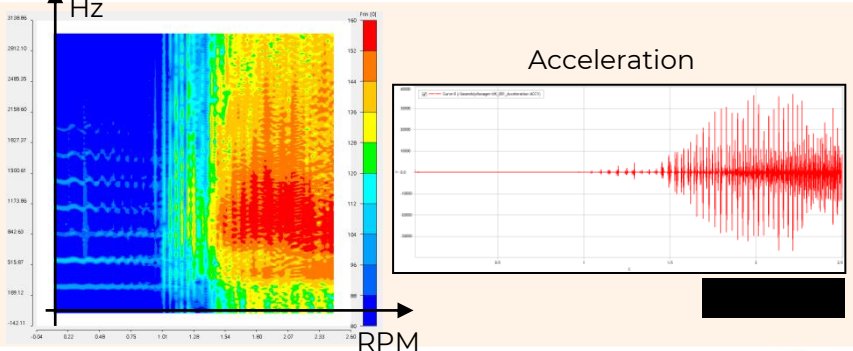
Bearing



BRG Clearance/Stiffness, Rigid housing, etc.



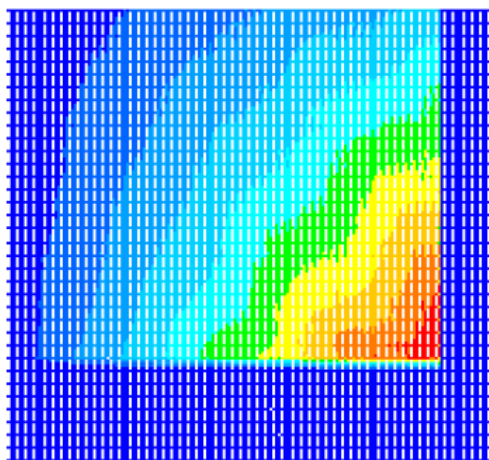
Noise Sources of E-Drivetrain: Gear Train

	Whine noise	Rattle noise
Causes	<ul style="list-style-type: none"> Time-varying mesh stiffness Manufacturing error Assemble error 	<ul style="list-style-type: none"> Varying driving torque/speed Large backlash Load fluctuation
Characteristics	<ul style="list-style-type: none"> High frequency noise. Related to the rotational speed. Harmonic components. 	<ul style="list-style-type: none"> Impulsive noise Broad-band noise
Sources	<ul style="list-style-type: none"> Periodic excitation force due to No. of tooth Peak to Peak transmission error One side contact <div>   </div>	<ul style="list-style-type: none"> Impulsive mesh force Unstable one side contact or two side contact <div>   </div>
Result		

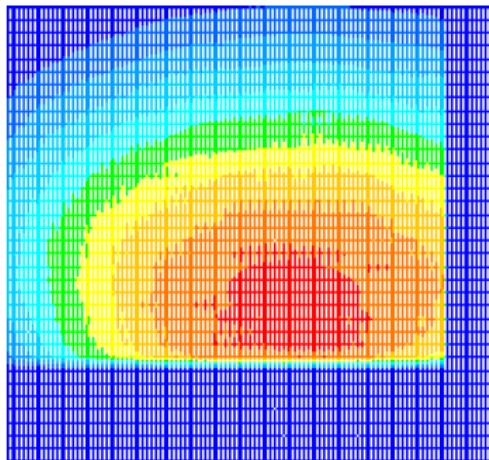
Types of NVH problems(gear whine)

How can improve?

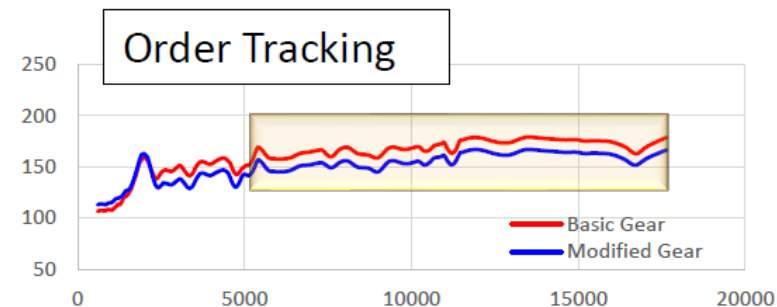
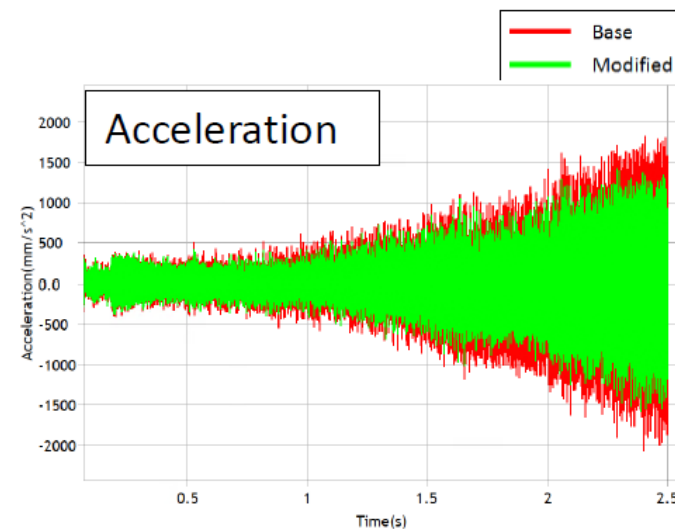
- Reduces the excitation force of the gear by improving the tooth characteristics through tooth shape correction



<TCP (Base)>

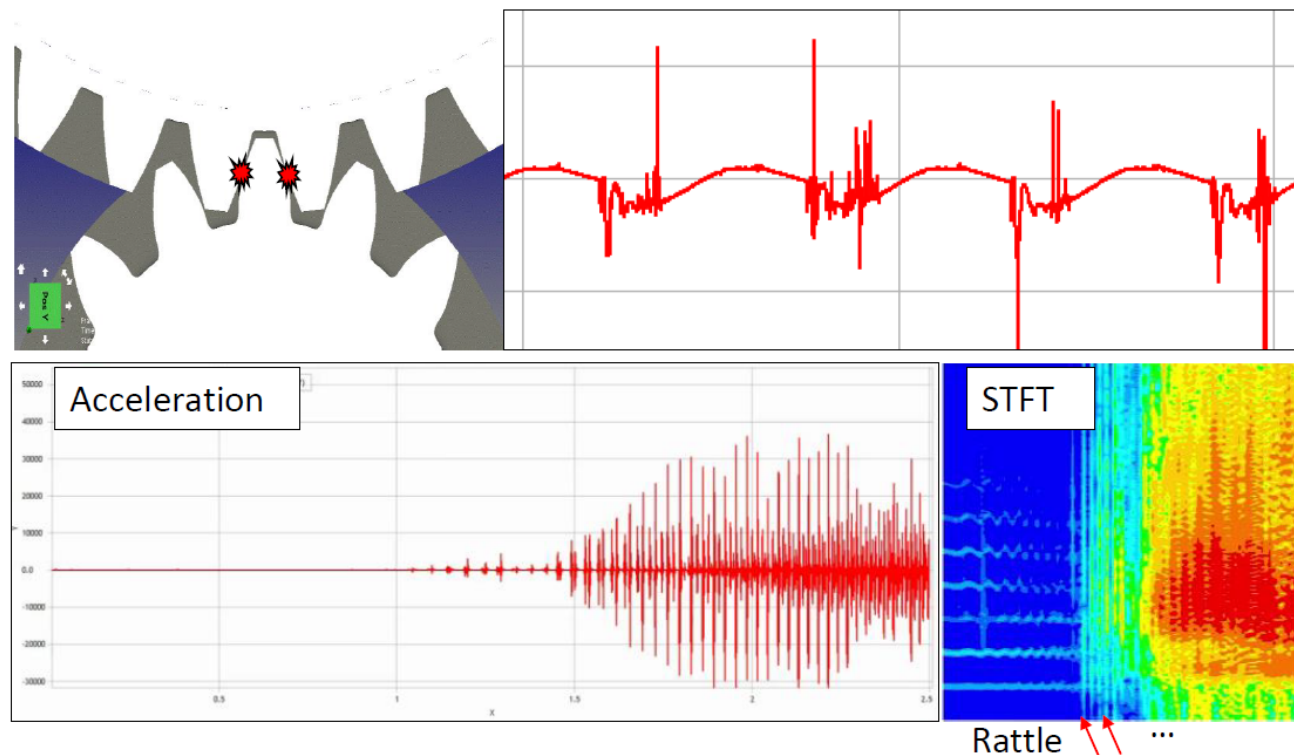


<TCP (Modified)>



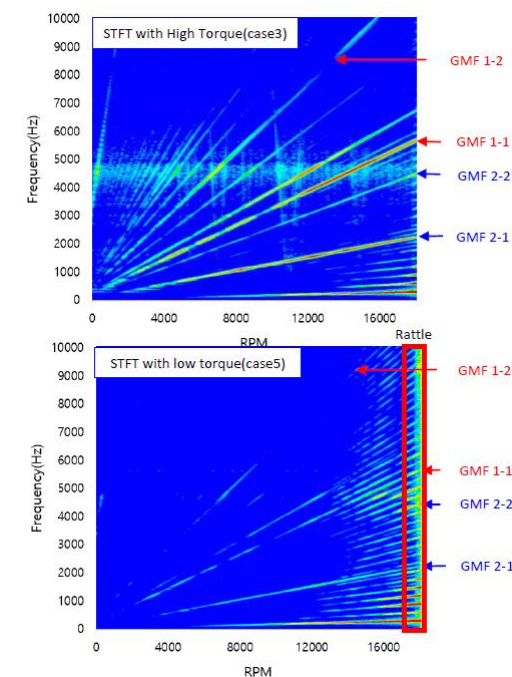
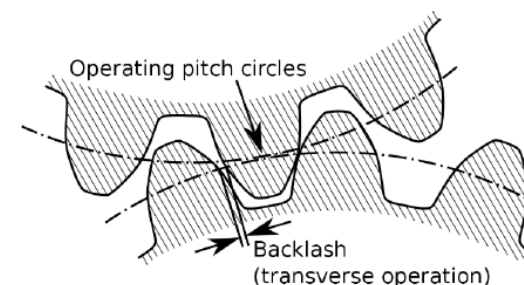
Types of NVH problems(gear rattle)

- The gear rattle noise happens in transmission system due to the torque fluctuation from the output shaft. Such a vibratory energy excitation of the gear teeth within the working clearance generates the annoying rattle noise.



How to improve?

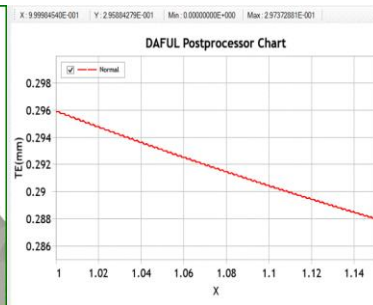
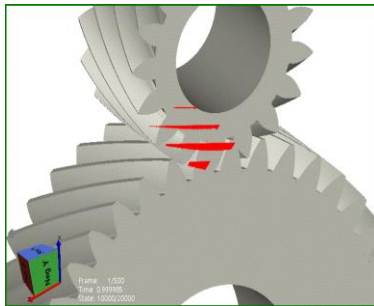
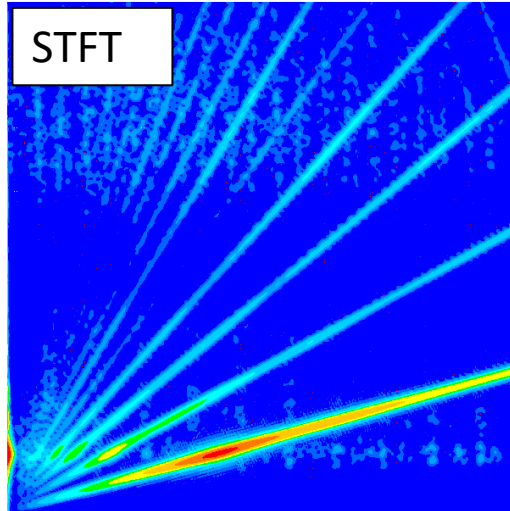
- Increase the torque, higher than the minimum required torque
- reduce the backlash of gear (use anti-backlash gear)



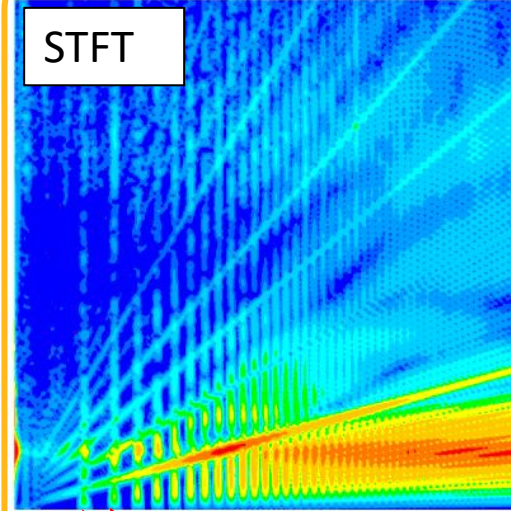
Types of NVH problems(gear fault)

- Gear Fault

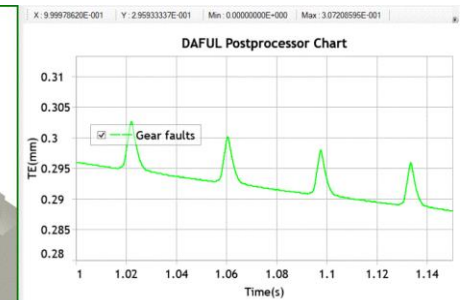
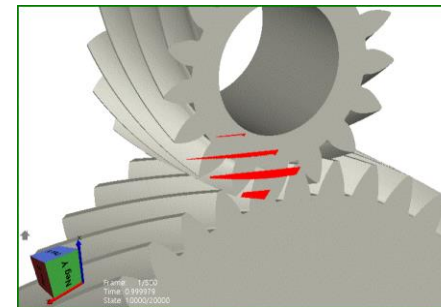
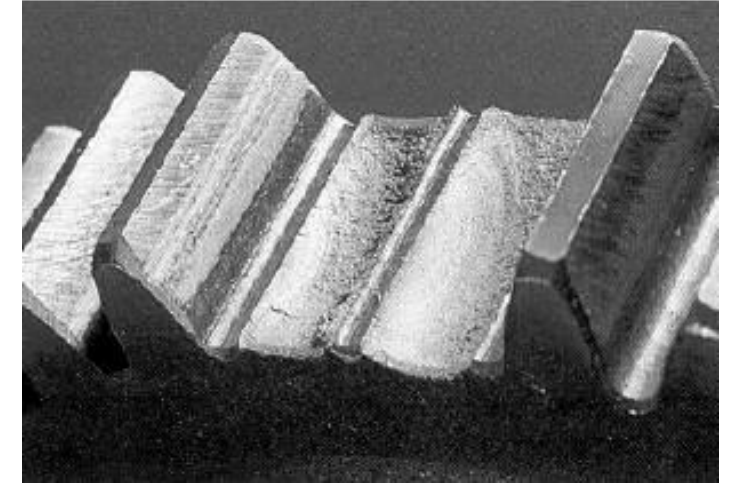
Without gear fault



With gear fault

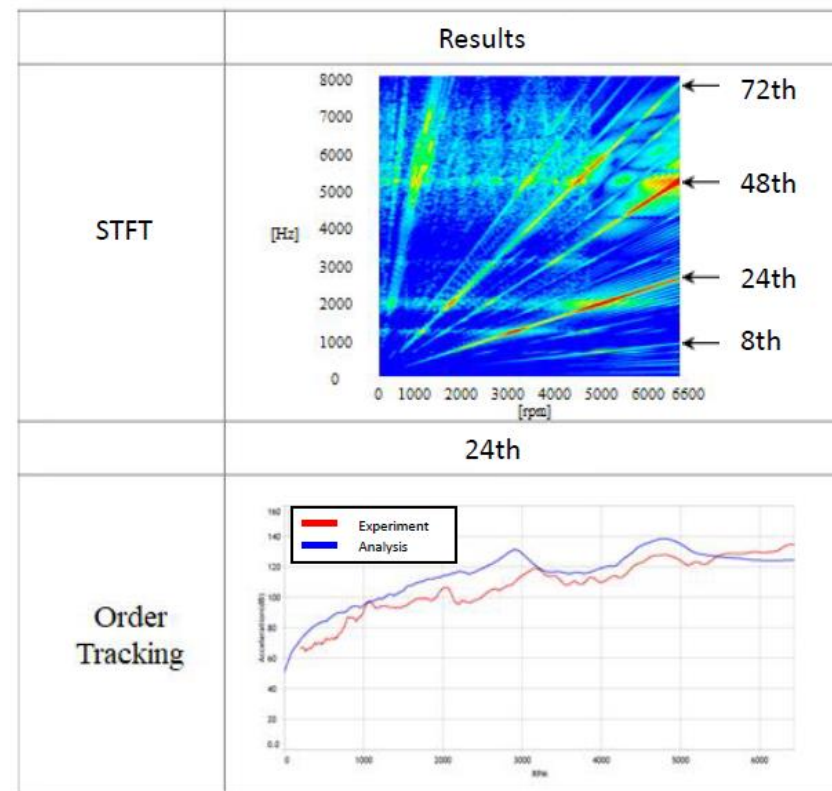
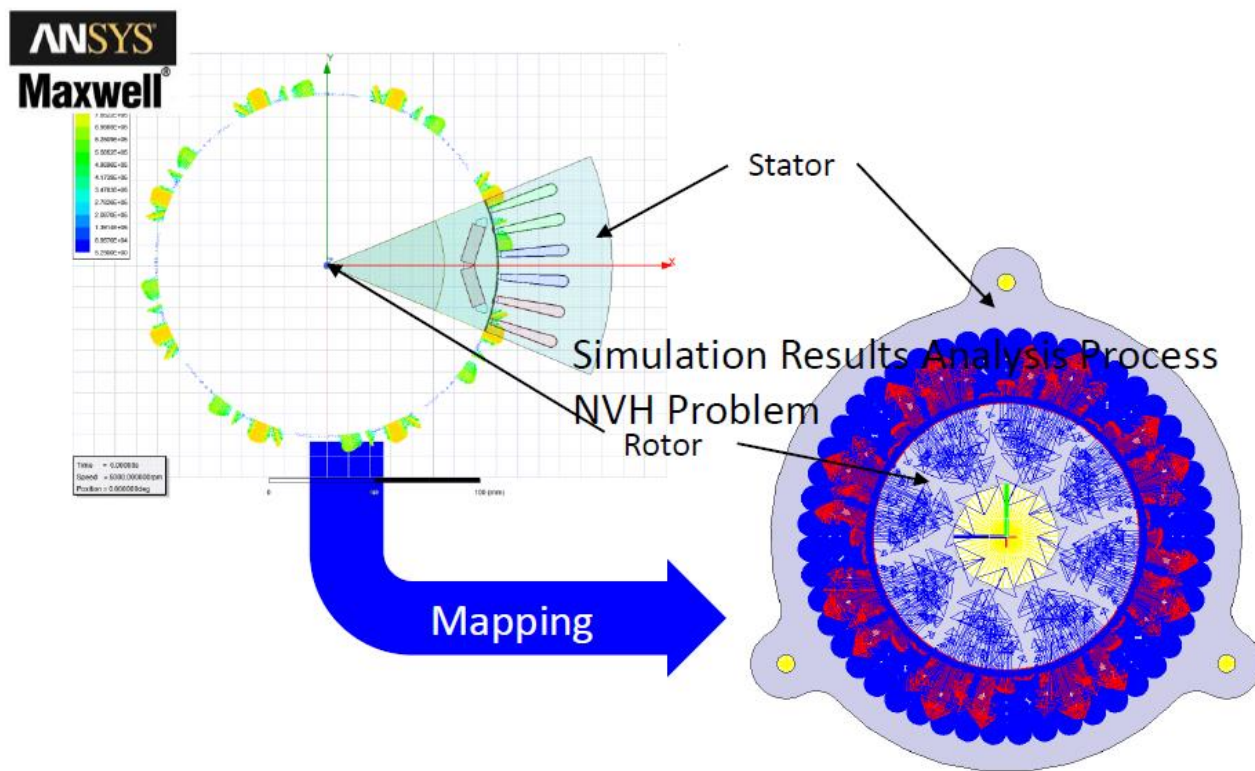


Rattle



Types of NVH problems(EM force)

- Additional excitation force coming from electromagnetic force needs to be considered as it can cause system resonance.

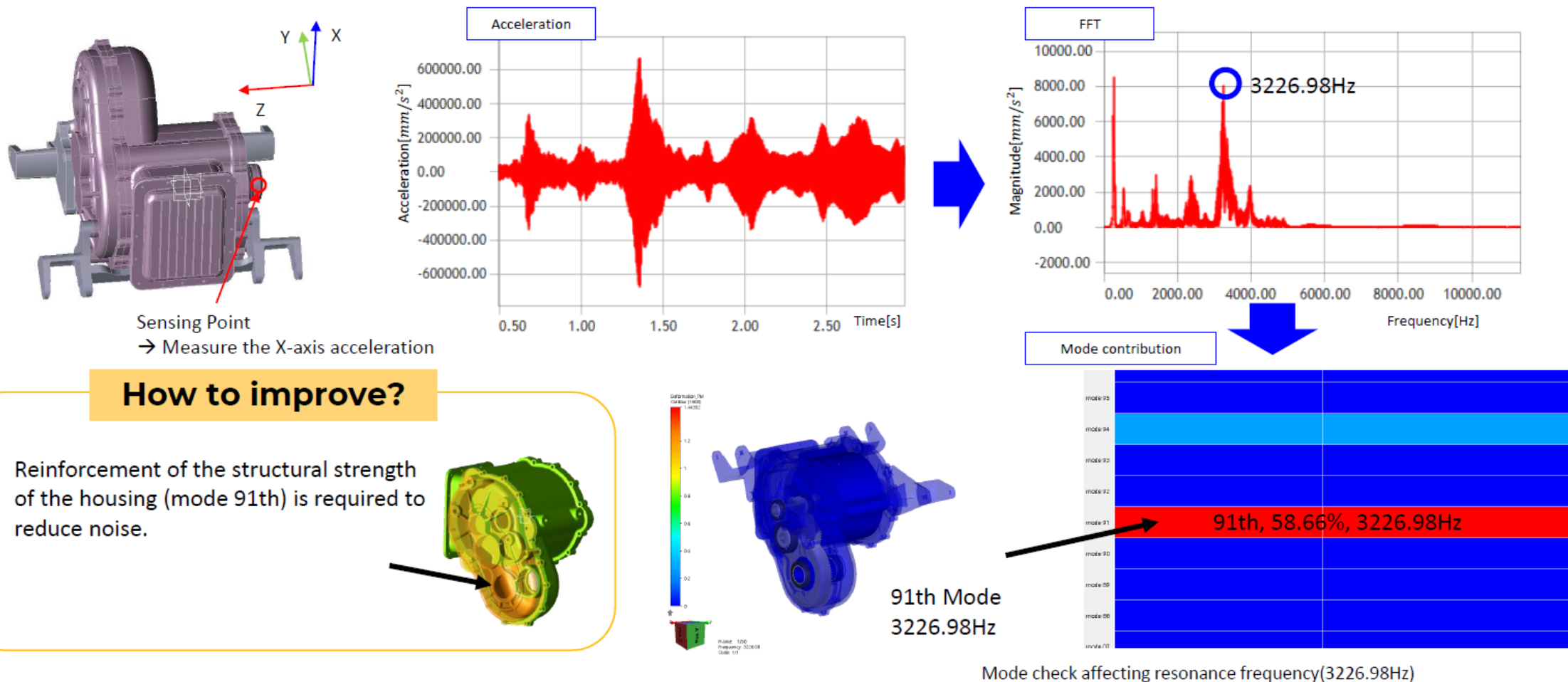


How can improve?

- Design plan to reduce electromagnetic excitation (Skew condition, etc.)
- System mode change to avoid problem areas

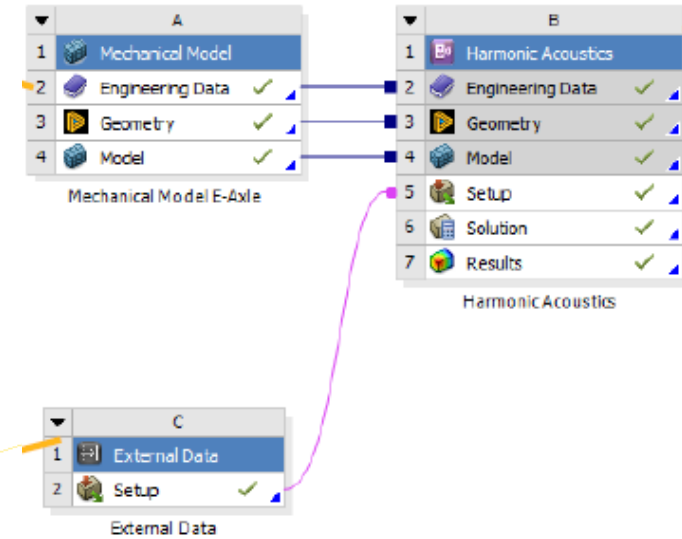
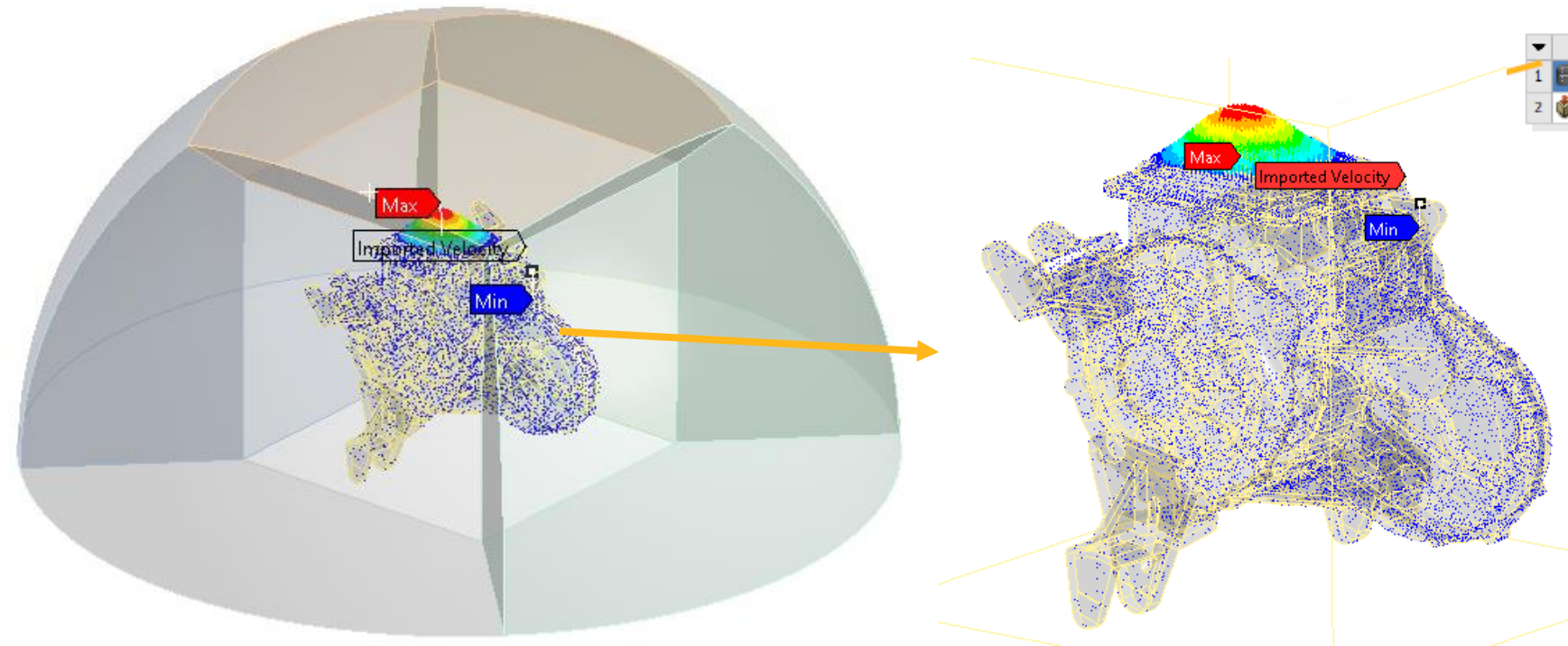
Types of NVH problems(EM force)

- To improve NVH performance, check the deformation mode at the resonant frequency and find the part that needs reinforcement.

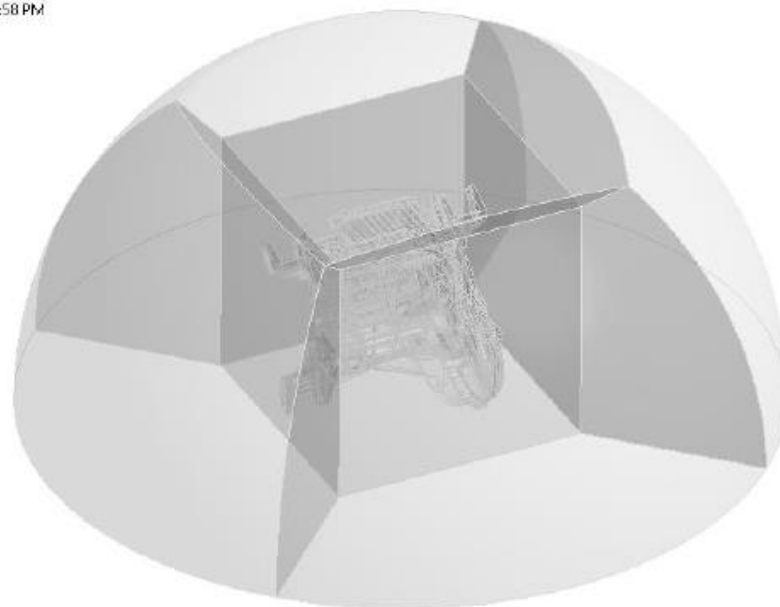
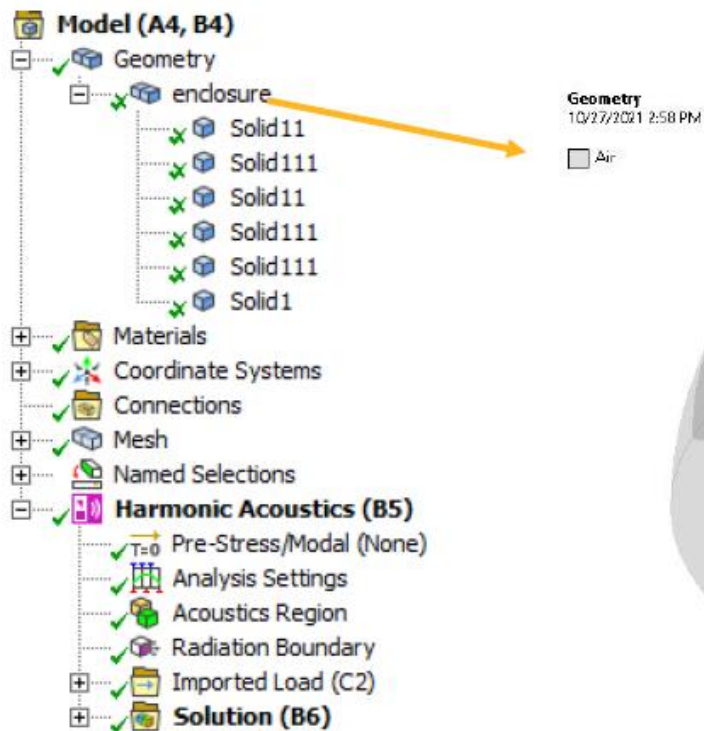


E-Drivetrain NVH Workflow: Velocity Mapping

- The velocity of the outer surface of the housing is mapped to the acoustics domain
- Automatic data transfer from Ansys Motion to Ansys Mechanical in Workbench

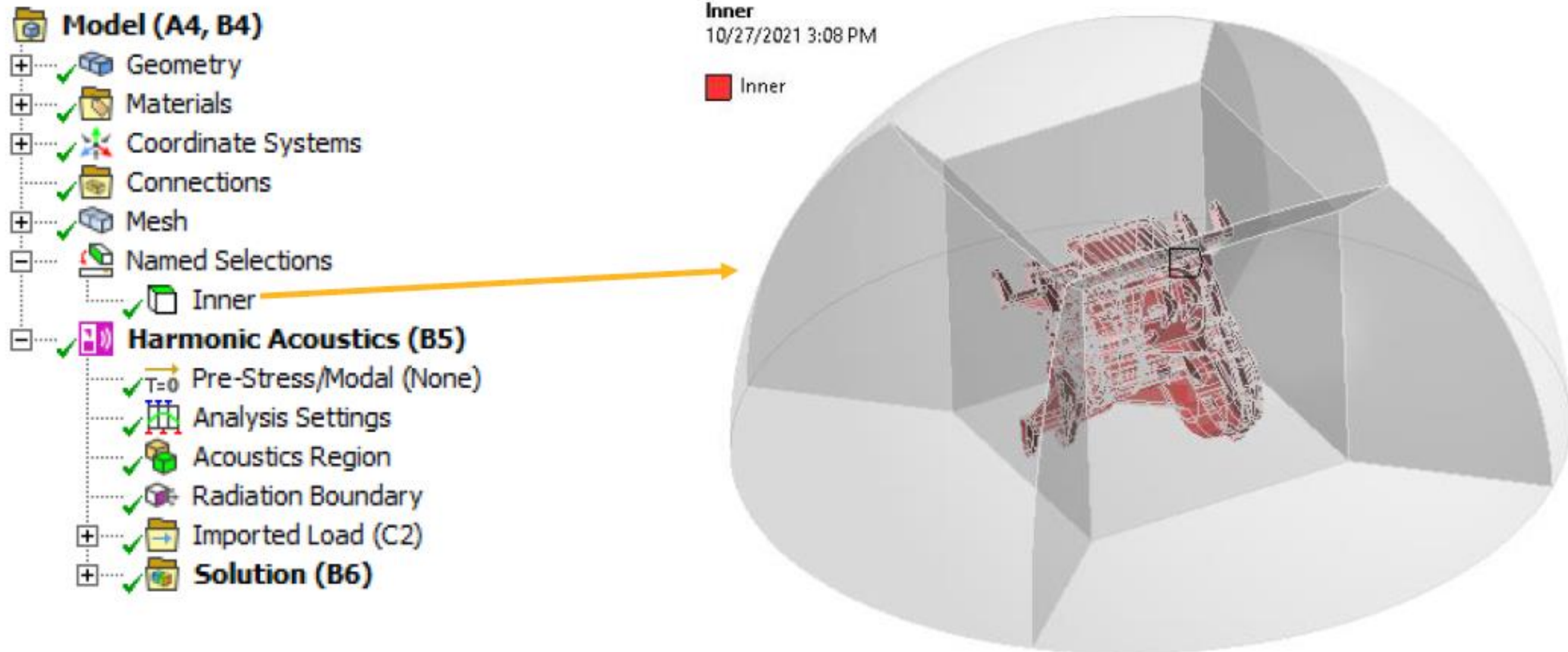


/ Setting enclosure

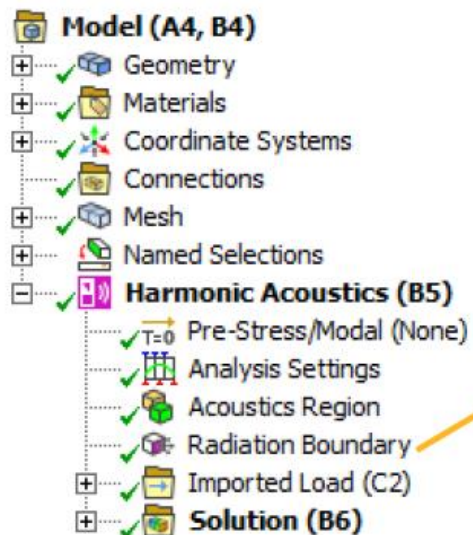


Details of "Multiple Selection"	
Graphics Properties	
Visible	Yes
Glow	0
Shininess	1
Transparency	0.2
Color	
Specularity	1
Definition	
Suppressed	No
ID (Beta)	
Stiffness Behavior	Flexible
Coordinate System	Default Coordinate System
Reference Temperature	By Environment
Treatment	None
Material	
Assignment	Air
Nonlinear Effects	Yes
Thermal Strain Effects	Yes
Bounding Box	
Properties	
Statistics	

/ Named selection on the interface



/ Radiation boundary

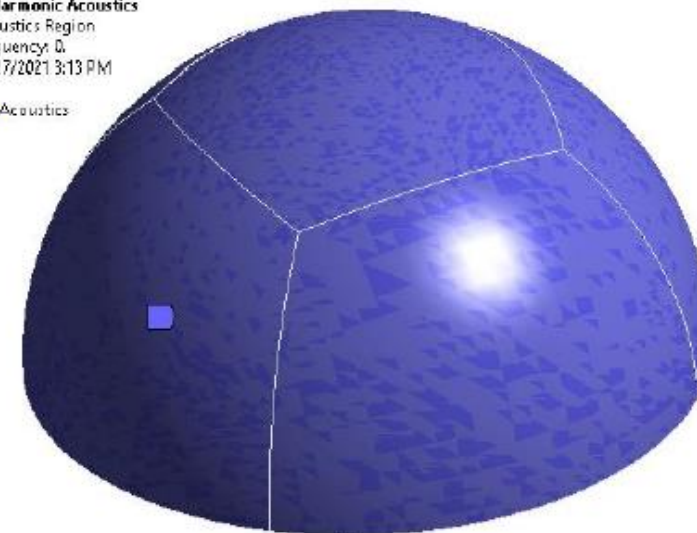


Details of "Radiation Boundary"

Scope	
Scoping Method	Geometry Selection
Geometry	5 Faces
Definition	
ID (Beta)	72
Type	Radiation Boundary
Suppressed	No

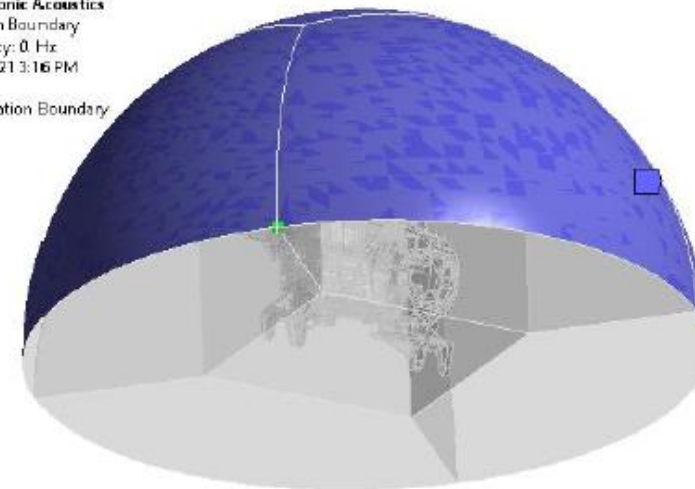
B: Harmonic Acoustics
Acoustics Region
Frequency: 0
10/27/2021 3:13 PM

Acoustics

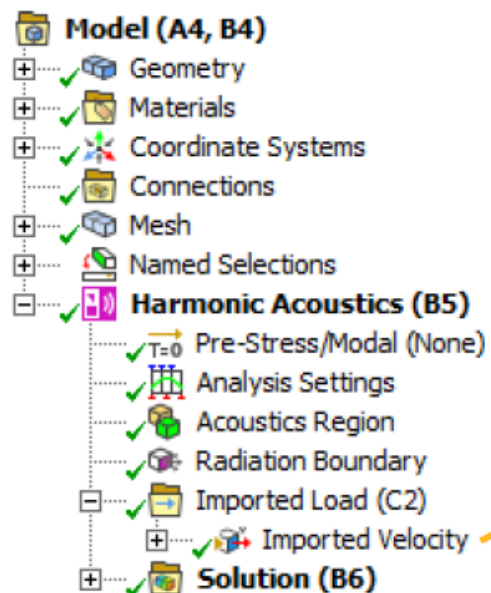


B: Harmonic Acoustics
Radiation Boundary
Frequency: 0 Hz
10/27/2021 3:16 PM

Radiation Boundary



/ Import velocity

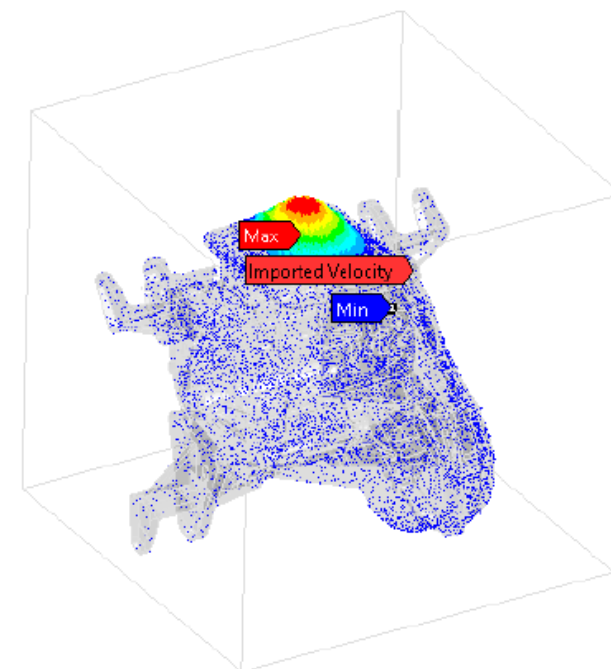
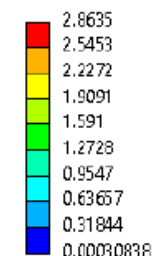


Details of "Imported Velocity"	
[-] Scope	
Scoping Method	Named Selection
Named Selection	Inner
[-] Definition	
Type	Imported Velocity
Tabular Loading	Program Controlled
Suppressed	No
Coordinate System	Source Coordinate System
[-] Graphics Controls	
By	Active Row
Active Row	1
Complex Component	Real
Component	All
Display Source Points	Off
Display Source Point Ids	Off
[-] Beta Options (Beta)	
Show Body Wireframe (Beta)	No
[-] Settings	
Mapping Control	Program Controlled
Mapping	Profile Preserving
Weighting	Triangulation
Transfer Type	Surface

Imported Velocity

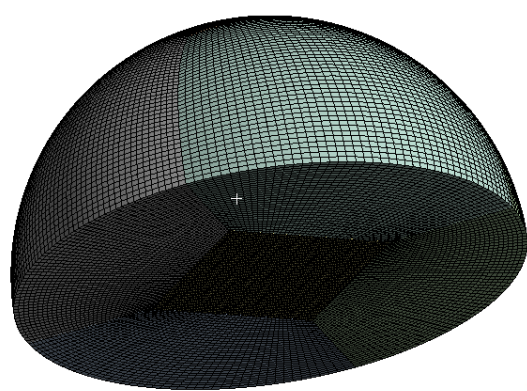
	X Component [Real] (mm/s)	X Component [Imag] (mm/s)	Y Component [Real] (mm/s)	Y Component [Imag] (mm/s)	Z Component [Real] (mm/s)	Z Component [Imag] (mm/s)	Analysis Frequency (Hz)	Program Controlled
1	File1:Velocity1	File1:Velocity2	File1:Velocity3	File1:Velocity4	File1:Velocity5	File1:Velocity6	1000	
2	File2:Velocity1	File2:Velocity2	File2:Velocity3	File2:Velocity4	File2:Velocity5	File2:Velocity6	1500	
3	File3:Velocity1	File3:Velocity2	File3:Velocity3	File3:Velocity4	File3:Velocity5	File3:Velocity6	2000	
4	File4:Velocity1	File4:Velocity2	File4:Velocity3	File4:Velocity4	File4:Velocity5	File4:Velocity6	2500	
5	File5:Velocity1	File5:Velocity2	File5:Velocity3	File5:Velocity4	File5:Velocity5	File5:Velocity6	3000	
6	File6:Velocity1	File6:Velocity2	File6:Velocity3	File6:Velocity4	File6:Velocity5	File6:Velocity6	3500	
7	File7:Velocity1	File7:Velocity2	File7:Velocity3	File7:Velocity4	File7:Velocity5	File7:Velocity6	4000	
8	File8:Velocity1	File8:Velocity2	File8:Velocity3	File8:Velocity4	File8:Velocity5	File8:Velocity6	4500	
9	File9:Velocity1	File9:Velocity2	File9:Velocity3	File9:Velocity4	File9:Velocity5	File9:Velocity6	5000	

B: Harmonic Acoustics
 Imported Velocity
 Frequency: 1000. Hz
 All
 Complex Component: Real
 Unit: mm/s
 Max: 2.8635
 Min: 0.00030838
 10/27/2021 3:18 PM

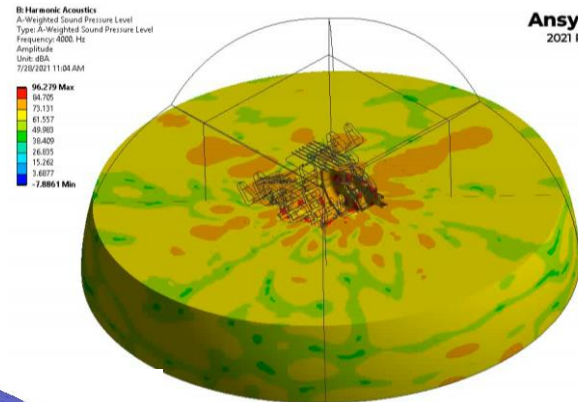


E-Drivetrain NVH Workflow: Harmonic Acoustics Analysis

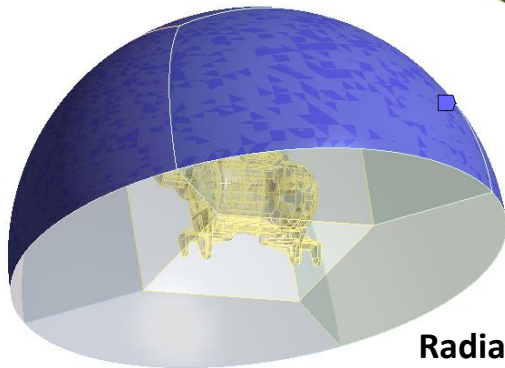
- Ansys Mechanical provides high-fidelity acoustics solver in frequency domain
- Estimation of the noise radiated from the vibrating housing of the E-drivetrain
- SPL, SWL and directivity patterns can be calculated



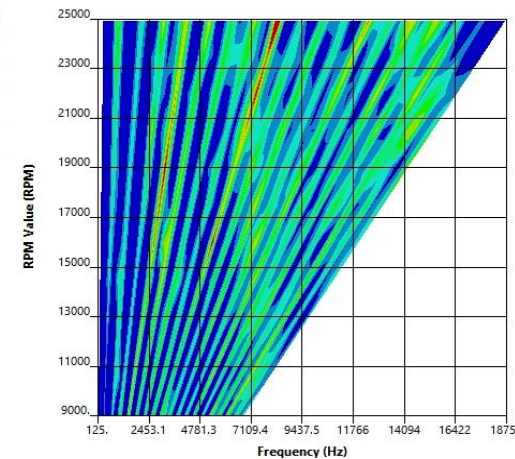
Acoustic Mesh



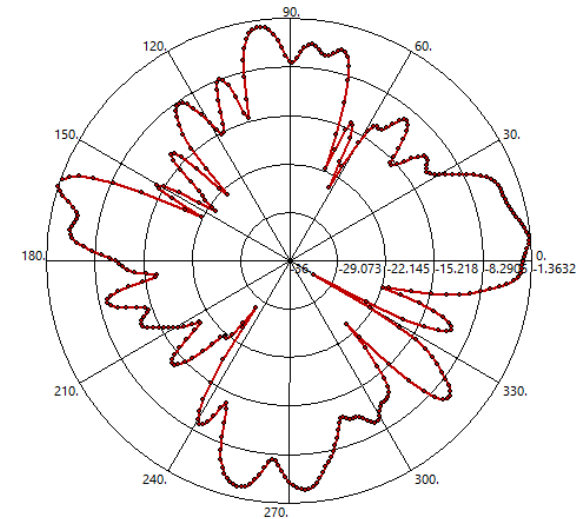
SPL



Radiation BC



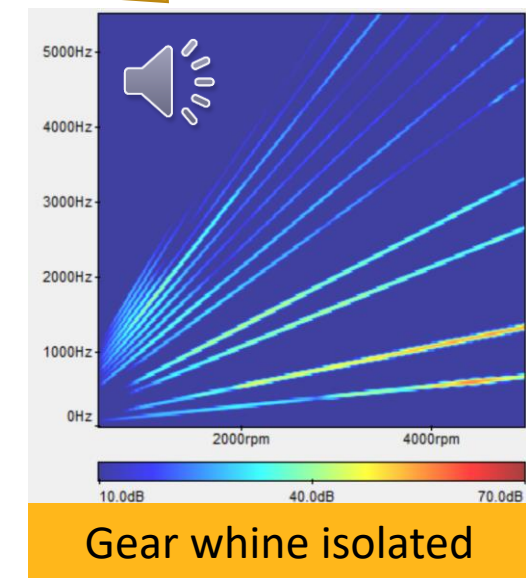
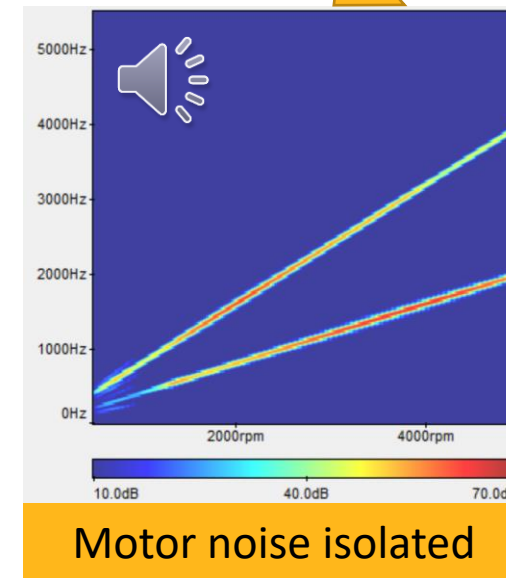
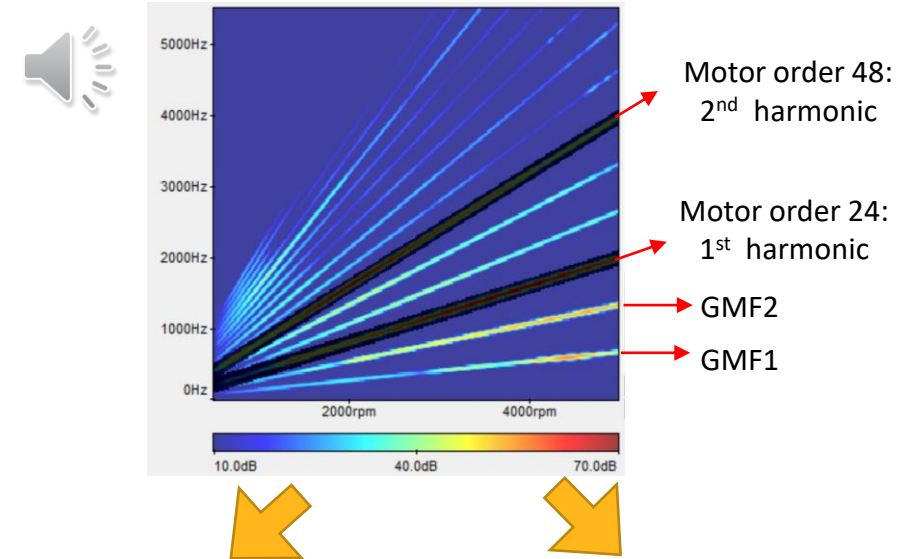
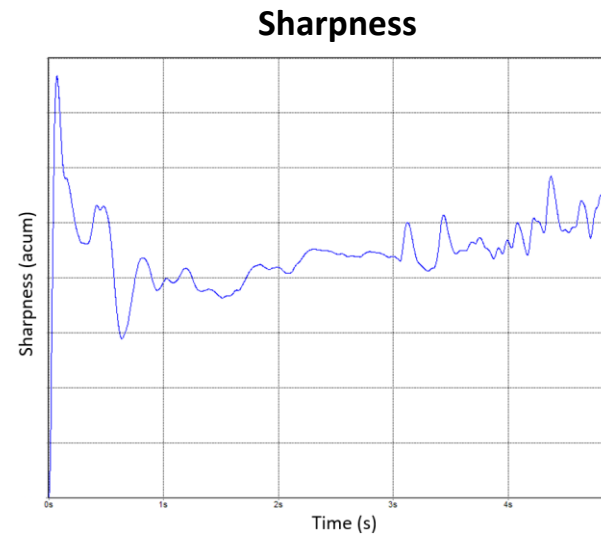
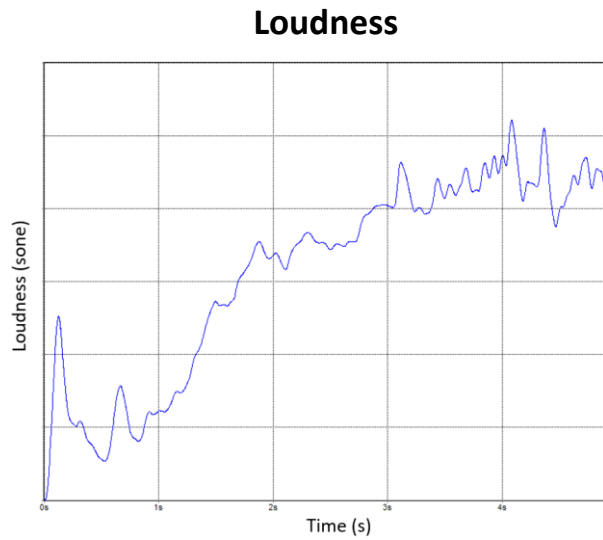
SPL vs Frequency & RPM



Directivity

E-Drivetrain NVH Workflow: Postprocessing of Simulated Noise

- Ansys VRX Sound enables further analysis of the simulated noise from Ansys Mechanical
 - Listen to the simulated noise
 - Order analysis
 - Psychoacoustics analysis
 - Noise isolation



/ Summary

- The integrated, Multiphysics workflow for the E-Drivetrain NVH analysis
 - Electromagnetic simulation to calculate the EM forces of a motor
 - Multi-body dynamics simulation to calculate structural response considering the motor and gear excitation
 - Acoustics simulation to predict the noise
 - Listen to the simulated noise
 - Psychoacoustic analysis to quantify human perception of noise
- Orders related to gear mesh and motor captured accurately in vibration and noise generated from the E-Drivetrain
- Such a workflow demonstrated enables engineers;
 - To reflect motor design, gear design, selection of bearings and housing design
 - To evaluate the NVH performance of E-powertrain in early design stage
 - To expedite design iterations to reduce noise